

Monomial ideals, binomial ideals, polynomial ideals

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Summary

These lectures are meant to provide a glimpse of the applications of toric geometry to singularity theory. They will illustrate some ideas and results of commutative algebra by showing the form which they take for very simple ideals of polynomial rings: monomial or binomial ideals, which can be understood combinatorially. Some combinatorial facts are the expression for monomial or binomial ideals of general results of commutative algebra or algebraic geometry such as resolution of singularities or the Briançon-Skoda theorem. In the opposite direction, I will show that there are methods which allow one to prove results about fairly general ideals by continuously specializing them to monomial or binomial ideals.

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1 Introduction

Let k be a field, and $k[u_1, \dots, u_d]$ (resp $k[[u_1, \dots, u_d]]$) the polynomial (resp. power series) ring in d variables.

If $d = 1$, given two monomials u^m, u^n , one divides the other, so that if $m > n$ say, a binomial $u^m - \lambda u^n = u^n(u^{m-n} - \lambda)$ with $\lambda \in k^*$ is, viewed now in $k[[u]]$, a monomial times a unit. For the same reason any series $\sum_i f_i u^i \in k[[u]]$ is the product of a monomial u^n , $n \geq 0$, by a unit of $k[[u]]$. Staying in $k[u]$, we can also view our binomial as the product of a monomial and a cyclic polynomial $u^{m-n} - \lambda$.

For $d = 2$, working in $k[[u_1, u_2]]$ we meet a serious difficulty: a series in two variables does not necessarily have a dominant term, that is, a term which divides all the others. The simplest example is the binomial $u_1^a - cu_2^b$ with $c \in k^*$. As we shall see, if we allow enough transformations, it is essentially the only example in dimension 2. So the behavior of a series $f(u_1, u_2)$ near the origin does not reduce to that of the product of a monomial $u_1^a u_2^b$ by a unit.

In general, for $d > 1$ and for a given $f(u_1, \dots, u_d) \in k[[u_1, \dots, u_d]]$, say $f = \sum_m f_m u^m$, where $m \in \mathbf{Z}_{\geq 0}^d$ and $u^m = u_1^{m_1} \dots u_d^{m_d}$, we can try to measure how different it is from a monomial times a unit by considering, the ideal of $k[[u_1, \dots, u_d]]$ or $k[u_1, \dots, u_d]$ generated by the monomials $\{u^m / f_m \neq 0\}$ which actually appear in f . Since both rings are noetherian, this ideal is finitely generated in both cases, and we are faced with the following problem:

Problem: Given an ideal generated by finitely many monomials (a *monomial ideal*) in $k[[u_1, \dots, u_d]]$ or $k[u_1, \dots, u_d]$, study how far it is from being principal.

We shall also meet a property stronger than principality: given a finitely generated ideal in a ring, the property that given any pair of its generators, one divides the other implies principality (exercise), but is stronger in general (take an ideal in a Principal Ideal Domain, such as \mathbf{Z} or a (non-monomial) ideal in $k[u]$); I shall call it *strong principality*. The integral domains in which every finitely generated ideal is strongly principal are known as *valuation rings*. Most of them are not noetherian.

Here we reach a bifurcation point in methodology:

-one approach is to generalize the notion of divisibility by studying all linear relations, with coefficients in the ambient ring, between our monomials. This leads to the construction of syzygies for the generators of our monomial ideal \mathcal{M} , or free resolutions for the quotient of the ambient ring by \mathcal{M} . There are many beautiful results in this direction. See Eisenbud's lectures and [St]. One is also led to try and compare monomials using *monomial orders* to produce Gröbner bases, since as soon as the ideal is not principal, deciding whether a given element belongs to it becomes arduous in general.

- Another approach is to try and force the ideal \mathcal{M} to become principal after a change of variables. It is the subject of the next section.

2 Strong principalization of monomial ideals by toric maps

In order to make a monomial ideal principal by changes of variables, the first thing to try is changes of variables which transform monomials into monomials, that is, which are themselves described by monomial functions:

$$\begin{aligned} u_1 &= y_1^{a_1^1} \cdots y_d^{a_1^d} \\ u_2 &= y_1^{a_2^1} \cdots y_d^{a_2^d} \\ &\vdots \\ &\vdots \\ u_d &= y_1^{a_d^1} \cdots y_d^{a_d^d} \end{aligned}$$

where we can consider the exponents of y_i appearing in the expressions of u_1, \dots, u_d as the coordinates of a vector a^i with integral coordinates. These expressions describe a monomial, or *toric*, map of d -dimensional affine spaces

$$\pi(a^1, \dots, a^d): \mathbf{A}^d(k) \rightarrow \mathbf{A}^d(k)$$

in the coordinates (y_i) for the first affine space and (u_i) for the second.

If we compute the effect of the change of variables on a monomial u^m , we see that

$$u^m \mapsto y_1^{\langle a^1, m \rangle} \cdots y_d^{\langle a^d, m \rangle}$$

Exercise: Show that the degree of the fraction field extension $k(u_1, \dots, u_d) \rightarrow k(y_1, \dots, y_d)$ determined by $\pi(a^1, \dots, a^d)$ is equal to the absolute value of the determinant of the vectors (a^1, \dots, a^d) . In particular it is equal to one (that is, our map $\pi(a^1, \dots, a^d)$ is birational) if and only if the determinant of the vectors (a^1, \dots, a^d) is ± 1 that is, (a^1, \dots, a^d) are a basis of the integral lattice \mathbf{Z}^d .

In view of the form of the transformation on monomials by our change of variables, it makes sense to introduce a copy of \mathbf{Z}^d where the exponents of our monomials dwell, and which we will denote by M , and a copy of \mathbf{Z}^d in which our vectors a^j dwell which we will call the *weight space* and denote by W . The lattices M and W are dual and we consider W as the integral lattice of the vector space $\check{\mathbf{R}}^d$ dual to the vector space \mathbf{R}^d in which our monomial exponents live. In this manner, we think of $m \mapsto \langle a^i, m \rangle$ as the linear form on M corresponding to $a^i \in W$.

Given two monomials u^m and u^n , the necessary and sufficient condition for the transform of u^n to divide the transform of u^m in $k[y_1, \dots, y_d]$ is that $\langle a^i, m \rangle \geq \langle a^i, n \rangle$ for all $i, 1 \leq i \leq d$. If we read this as $\langle a^i, m-n \rangle \geq 0$ for all $i, 1 \leq i \leq d$ and seek a symmetric formulation, we are led to introduce the rational hyperplane H_{m-n} in $\check{\mathbf{R}}^d$ which is dual to the vector $m-n \in M$ and obtain the following elementary but fundamental fact, where the transform of a monomial is nothing but its composition with the map $\pi(a^1, \dots, a^d)$ in the coordinates (y_1, \dots, y_d) :

Lemma 2.1. *A necessary and sufficient condition for the transform of one of the monomials u^m, u^n by the map $\pi(a^1, \dots, a^d)$ to divide the transform of the other in $k[y_1, \dots, y_d]$ is that all the vectors a^j lie on the same side of the hyperplane H_{m-n} in $\check{\mathbf{R}}_{\geq 0}^d$.*

Remark that the condition is non empty if and only if one of the monomials u^m, u^n does not already divide the other in $k[u_1, \dots, u_d]$, because to say that such divisibility does not occur is to say that the equation of the hyperplane H_{m-n} does not have all its coefficients of the same sign, and therefore separates in two regions the first quadrant $\check{\mathbf{R}}_{\geq 0}^d$ where our vectors a^j live.

To force one monomial to divide the other in the affine space $\mathbf{A}^d(k)$ with coordinates (y_i) is nice but not extremely useful since it provides information on the original monomials only in the image of the map $\pi(a^1, \dots, a^d)$ in the affine space $\mathbf{A}^d(k)$ with coordinates (u_i) , which is a constructible subset different from $\mathbf{A}^d(k)$. It is much more useful to find a proper and birational (hence surjective) map of algebraic varieties over k $\pi: Z \rightarrow \mathbf{A}^d(k)$ such that the compositions with π of our monomials generate a sheaf of ideals in Z which is *locally* principal; if you prefer, Z should be covered by affine charts U such that if our monomial ideal \mathcal{M} is generated by u^{m^1}, \dots, u^{m^g} , the ideal $(u^{m^1} \circ \pi, \dots, u^{m^g} \circ \pi)|_U$ is principal, or strongly principal.

Toric geometry provides a way to do this:

A rational fan with $\check{\mathbf{R}}_{\geq 0}^d$ as support is a finite collection Σ of strictly convex rational cones $(\sigma_\alpha)_{\alpha \in A}$ with the following properties:

- 1) The union of all the $(\sigma_\alpha)_{\alpha \in A}$ is the closed first quadrant $\check{\mathbf{R}}_{\geq 0}^d$ of $\check{\mathbf{R}}^d$.
- 2) Each face of a $\sigma_\alpha \in \Sigma$ is in Σ ;
- 3) each intersection $\sigma_\alpha \cap \sigma_\beta$ is a face of σ_α and of σ_β .

In general, the *support* of a fan Σ is defined as $\bigcup_{\alpha \in A} \sigma_\alpha$.

Recall that a cone is *strictly convex* if it contains no positive dimensional vector subspace, and cones contained in the first quadrant must be strictly convex.

A cone $\sigma \subset \check{\mathbf{R}}^d$ is strictly convex if and only if its convex dual

$$\check{\sigma} = \{m \in \mathbf{R}^d / \langle m, a \rangle \geq 0 \text{ for all } a \in \sigma\}$$

has a non empty interior in \mathbf{R}^d .

A rational convex cone is one bounded by finitely many hyperplanes whose equations have rational (or equivalently, integral) coefficients. An equivalent definition is that a rational convex cone is the cone positively generated by finitely many vectors with integral coordinates.

A fan is said to be *regular* if each of its k -dimensional cones is generated by k integral vectors (it is a simplicial cone) which form part of a basis of the integral lattice. If $k = d$ it means that their determinant is ± 1 .

If we go back to our monomial map, assuming that the determinant of the vectors (a^1, \dots, a^d) is ± 1 , we can express the y_j as monomials in the u_i ; the matrix of exponents will then be the inverse of the matrix (a^1, \dots, a^d) , and

have some negative entries. Monomials with possibly negative exponents will be called *Laurent monomials* here.

If $\sigma = \langle a^1, \dots, a^d \rangle$, the cone positively generated by the vectors a^1, \dots, a^d , then the monomials in y_1, \dots, y_d , viewed as Laurent monomials in u_1, \dots, u_d via the expression of the y_j as Laurent monomials in the u_i , correspond to the integral points of the dual convex cone

$$\check{\sigma} = \{x \in \mathbf{R}^d / \ell(x) \geq 0 \ \forall \ell \in \sigma\}$$

of σ , i.e., those points $m \in \mathbf{Z}^d$ such that $\langle a^i, m \rangle \geq 0$ for all $1 \leq i \leq d$. So we can identify the polynomial algebra $k[y_1, \dots, y_d]$ with the algebra $k[\check{\sigma} \cap M]$ of the semigroup $\check{\sigma} \cap M$ with coefficients in k . Since σ is contained in the first quadrant of $\check{\mathbf{R}}^d$, its convex dual $\check{\sigma}$ contains the first quadrant of \mathbf{R}^d , so we have a graded inclusion of algebras

$$k[\mathbf{R}_{\geq 0}^d \cap M] = k[u_1, \dots, u_d] \subset k[\check{\sigma} \cap M] = k[y_1, \dots, y_d],$$

the inclusion being described by sending each variable u_i to a monomial in y_1, \dots, y_d as we did in the beginning.

This slightly more abstract formulation has the following use: Given a fan in $\check{\mathbf{R}}^d$, to each of its cones σ we can associate the algebra $k[\check{\sigma} \cap M]$, even if the strictly convex cone σ is not generated by d vectors with determinant ± 1 .

By a lemma of Gordan (see [TE]), it is finitely generated, so it corresponds to an affine algebraic variety $X_\sigma = \text{Spec } k[\check{\sigma} \cap M]$. This variety is a d -dimensional affine space if and only if the cone $\check{\sigma}$ (or σ) is d -dimensional and generated by vectors which form a basis of the integral lattice of $\check{\mathbf{R}}^d$. It is, however, always normal and with rational singularities only (see [TE]) and moreover it is rational, which means that the field of fractions of $k[\check{\sigma} \cap M]$ is $k(u_1, \dots, u_d)$.

If two cones σ_α and σ_β have a common face $\tau_{\alpha\beta}$, the affine varieties X_{σ_α} and X_{σ_β} can be glued up along the open set corresponding to $X_{\tau_{\alpha\beta}}$ which they have in common. By this process, the fan Σ gives rise to an algebraic variety which is proper over $\mathbf{A}^d(k)$

$$\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$$

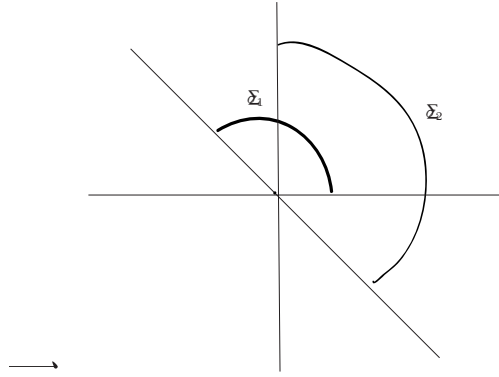
The variety $Z(\Sigma)$ is covered by affine charts corresponding to the d -dimensional cones σ of Σ and in each of these charts the map $\pi(\Sigma)$ corresponds to the inclusion of algebras $k[u_1, \dots, u_d] \subset k[\check{\sigma} \cap M]$. If σ is generated by d vectors with determinant ± 1 , i.e., which form a basis of the integral lattice, the second algebra is a polynomial ring $k[y_1, \dots, y_d]$ and the inclusion is given by the monomial expression we started from. Let us give the following definition, and remember that $\{0\}$ is a face of each strictly convex cone:

Definition. A convex polyhedral cone σ is compatible with a convex polyhedral cone σ' if $\sigma \cap \sigma'$ is a face of each. A fan is compatible with a polyhedral cone if each of its cones is.

Lemma 2.2. Given two monomials u^m, u^n , if we can find a fan Σ which is compatible with the hyperplane H_{m-n} in the weight space, then in each chart of $Z(\Sigma)$ the transform of one of our monomials will divide the other.

Proof. This follows from Lemma 2.1. ○

Example: In dimension $d = 2$, let us seek to make one of the two monomials (u_1, u_2) divide the other after a monomial transformation. The hyperplane in the weight space is $w_1 = w_2$; its intersection with the first quadrant defines a fan whose cones are the two cones σ_1 and σ_2 generated by $a^1 = (0, 1), a^2 = (1, 1)$ and by $b^1 = (1, 1), b^2 = (0, 1)$ and their faces. The semigroup of integral points of $\check{\sigma}_1 \cap M$ is generated by $(1, 0), (-1, 1)$, which correspond respectively to the monomials $y_1 = u_1, y_2 = u_1^{-1}u_2$ and the semigroup of integral points of $\check{\sigma}_2 \cap M$ is generated by $(0, 1), (1, -1)$, which correspond respectively to the monomials $y'_2 = u_2, y'_1 = u_1u_2^{-1}$. There is a natural isomorphism of the open sets where $u_1 \neq 0, u_2 \neq 0$ and gluing up gives the two-dimensional subvariety of $\mathbf{A}^2(k) \times \mathbf{P}^1(k)$ defined by $t_2u_1 - t_1u_2 = 0$, where $(t_1 : t_2)$ are the homogeneous coordinates on $\mathbf{P}^1(k)$, with its natural projection to $\mathbf{A}^2(k)$: it is the blowing-up of the origin in $\mathbf{A}^2(k)$.



Now if we have a finite number of distinct monomials $\neq 1$, say u^{m^1}, \dots, u^{m^a} , and if we can find a fan Σ with support $\check{\mathbf{R}}_{\geq 0}^d$ and compatible with *all* the hyper-

planes $H_{m^s - m^t}$, $1 \leq s, t \leq q, s \neq t$, this will give us an algebraic (toric) variety $Z(\Sigma)$, possibly singular and endowed with a *proper surjective* map $\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$ such that the pull back by the map $\pi(\Sigma)$ of the ideal \mathcal{M} generated by our monomials is strongly principal in each chart. The properness and surjectivity are ensured (see [TE]) by the fact that the support of Σ is $\mathbf{R}_{\geq 0}^d$.

Our collection of hyperplanes ($H_{m^s - m^t}$, $1 \leq s, t \leq q, s \neq t$) through the origin in fact defines a fan $\Sigma_0(F)$ which depends only upon the finite set $F = \{m^1, \dots, m^q\}$ of elements of \mathbf{Z}^d : take as cones the closures of the connected components of the complement in $\mathbf{R}_{\geq 0}^d$ of the union of all the hyperplanes. They are strictly convex rational cones because they lie in the first quadrant and are bounded by hyperplanes whose equations have integral coefficients. Add all the faces of these cones, and we have a fan, of course not regular in general. To say that a monomial ideal generated by monomials in the generators of the algebra $k[\check{\sigma} \cap M]$ is locally strongly principal is not nearly as useful when these generators do not form a system of coordinates as when they do. However, it is important to note that we first make our ideal \mathcal{M} locally strongly principal by the map $\pi(\Sigma_0): Z(\Sigma_0) \rightarrow \mathbf{A}^d(k)$, and then resolve the singularities of $Z(\Sigma_0)$ by a toric map.

The second step corresponds to a refinement of Σ_0 into a regular fan Σ , where refinement means that each cone of the second fan is contained in a cone of the original.

This is always possible in view of the:

Theorem 2.3. (Kempf, Knudsen, Mumford, St. Donat, see [TE]) *Given a rational fan, it is always possible to refine it into a regular fan.*

From this follows:

Theorem 2.4. *Let k be a field. Given a monomial ideal \mathcal{M} in $k[u_1, \dots, u_d]$, there exists a fan Σ_0 with support $\mathbf{R}_{\geq 0}^d$ such that, given any regular refinement Σ of Σ_0 , the associated proper birational toric map of non singular toric varieties*

$$\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$$

has the property that the transform of \mathcal{M} is strongly principal in each chart.

Remark. *By construction, for each chart $Z(\sigma)$ of $Z(\Sigma)$ there is an element of \mathcal{M} whose transform generates the ideal $\mathcal{M}\mathcal{O}_{Z(\sigma)}$. This element cannot be the same for all charts unless \mathcal{M} is already principal.*

To see this, assume that there is a monomial u^n whose transform generates $\mathcal{M}\mathcal{O}_{Z(\Sigma)}$ in every chart. This means that every simplicial cone σ of our fan with support $\mathbf{R}_{\geq 0}^d$ is in the positive side of all the hyperplanes H_{m-n} for all the other monomials u^m generating \mathcal{M} . But this is possible only if none of these hyperplanes meets the positive quadrant outside $\{0\}$, which means that u^n divides all the other u^m .

Remark. (Strong principalization and blowing-up) *Given a finitely generated ideal I in a commutative integral domain R , there is a proper birational map $\pi: B(I) \rightarrow \text{Spec}R$, unique up to unique isomorphism, with the property that the ideal sheaf $I\mathcal{O}_{B(I)}$ generated by the compositions with π of the elements of I is locally principal and generated by a non zero divisor (that is, an invertible ideal), and that any map $W \rightarrow \text{Spec}R$ with the same property factors uniquely through π . The map π is called the blowing-up of I in R , or in $\text{Spec}R$.*

The blowing-up is in particular independent of the choice of generators of I . Since a product of ideals is invertible if and only if each ideal is, for $I = (f_1, \dots, f_s)R$, the blowing-up in $\text{Spec}R$ of the ideal $J = \prod_{i < j} (f_i, f_j)R$ will make I strongly principal.

If I is a monomial ideal in $k[u_1, \dots, u_d]$, according to [TE], the blowing-up of I followed by normalization is the equivariant map associated to the fan dual to the Newton polyhedron of I , two notions defined below respectively in section 5 and in the Appendix. The reader is encouraged to check that the fan just mentioned admits the fan Σ_0 introduced above as a refinement, illustrating the general fact that a strong principalization map factors through the blowing-up.

Strong principalization was stressed in these lectures because it is directly linked with the resolution of singularities of binomial ideals explained in section 6.

Exercise. *Check that one can in all statements and proofs in this section replace the positive quadrant of \mathbf{R}^d by any strictly convex rational cone $\sigma_0 \subset \mathbf{R}^d$. The affine space $\mathbf{A}^d(k)$ is then replaced by the affine toric variety X_{σ_0} .*

3 The integral closure of ideals

Given a finite set $F = \{m^1, \dots, m^q\}$ of elements of \mathbf{Z}^d , let us define its *support function* as follows: it is the function $h_F: \check{\mathbf{R}}^d \rightarrow \mathbf{R}$ defined by

$$h_F(\ell) = \min_{1 \leq s \leq q} \ell(m^s).$$

For reasons which will become apparent, I denote the convex hull of F by \overline{F} . It is a classical result on convexity, presenting the convex hull of a set as the intersection of the half-spaces containing that set, that the convex hull of F is given by

$$\overline{F} = \{n \in \mathbf{R}^d / \ell(n) \geq h_F(\ell) \quad \forall \ell \in \check{\mathbf{R}}^d\}.$$

It is often found in convexity books as saying that a convex set is the intersection of the half-spaces determined by its support hyperplanes. The same proof shows that the “positive convex hull” is defined by the same inequalities restricted to the linear forms which are in the positive quadrant of $\check{\mathbf{R}}^d$:

$$\overline{\bigcup_{1 \leq s \leq q} (m^s + \mathbf{R}_{\geq 0}^d)} = \{n \in \mathbf{R}^d / \ell(n) \geq h_F(\ell) \quad \forall \ell \in \check{\mathbf{R}}_{\geq 0}^d\}.$$

Lemma 3.1. *The support function h_F is linear in each cone of the fan $\Sigma_0(F)$ introduced in section 2.*

Proof. It follows directly from the definitions. \circlearrowright

Let us choose a strongly principalizing map $\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$ with Σ a refinement of $\Sigma_0(F)$ as in Theorem 2.4. Then $Z(\Sigma)$ is normal by [TE] (it is regular if Σ is regular), and $\pi(\Sigma)$ is proper and birational. Let u^n be a monomial in $k[u_1, \dots, u_d]$. Given a chart X_σ of $Z(\Sigma)$, corresponding to $\sigma \in \Sigma$, a necessary and sufficient condition for $u^n \circ \pi(\Sigma)$ to belong in $k[\check{\sigma} \cap M]$ to the ideal generated by the transforms of the generators of \mathcal{M} is that we have $\ell(n) \geq h_F(\ell)$ for all $\ell \in \sigma$: by Lemma 3.1, we have for some $t \in \{1, \dots, q\}$ that $h_F(\ell) = \ell(m^t)$ for all $\ell \in \sigma$, and then by definition of $\check{\sigma}$ our inequality means that the quotient of the transform of u^n by the transform of u^{m^t} is in $k[\check{\sigma} \cap M]$, which means that $u^n k[\check{\sigma} \cap M] \subset \mathcal{M}k[\check{\sigma} \cap M]$. For this to be true in all charts it is necessary and sufficient, as we saw, that n should be in the convex hull $\overline{\bigcup_{1 \leq s \leq q} (m^s + \mathbf{R}_{\geq 0}^d)}$. So we have finally, using a little sheaf-theoretic language (in particular, $u^n \mathcal{O}_{Z(\Sigma)} = u^n \circ \pi(\Sigma)$ viewed as a global section of the sheaf $\mathcal{O}_{Z(\Sigma)}$):

Lemma 3.2. *We have $u^n \mathcal{O}_{Z(\Sigma)} \in \mathcal{M} \mathcal{O}_{Z(\Sigma)}$ if and only if n is in the convex hull of $\bigcup_{1 \leq s \leq q} (m^s + \mathbf{R}_{\geq 0}^d)$.*

Now one defines integral dependance over an ideal (a concept which goes back to Prüfer or even Dedekind) as follows:

Definition. *An element h of a commutative ring R is integral over an ideal I of R if it satisfies an algebraic relation*

$$h^r + a_1 h^{r-1} + \dots + a_r = 0 \quad \text{with } a_i \in I^i \quad \text{for } 1 \leq i \leq r.$$

It is not difficult to see that the set of elements integral over I is an ideal \bar{I} containing I and contained in \sqrt{I} ; it is the *integral closure* of I . We have the following characterization in algebraic geometry, which follows from the Riemann extension theorem:

Proposition 3.3. (see [Li-T]) *Let k be a field and R a localization of a finitely generated reduced k -algebra. Let I be an ideal of R and $h \in R$. The element h is integral over I if and only if there exists a proper and birational morphism $t: Z \rightarrow \text{Spec} R$ such that $h \circ t \in I \mathcal{O}_Z$ (i.e., $h \mathcal{O}_Z \in I \mathcal{O}_Z$), and then this inclusion holds for any such morphism such that Z is normal and $I \mathcal{O}_Z$ is invertible.*

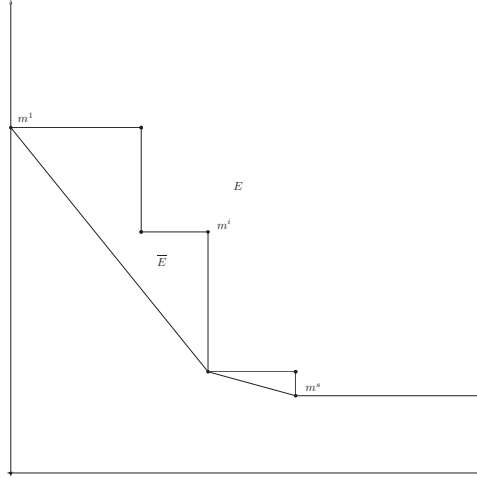
From this follows the interpretation of the Lemma:

Proposition 3.4. *The integral closure in $k[u_1, \dots, u_d]$ of a monomial ideal generated by the monomials u^{m^1}, \dots, u^{m^q} is the monomial ideal generated by the monomials with exponents in the convex hull \bar{E} of $E = \bigcup_{1 \leq s \leq q} (m^s + \mathbf{R}_{\geq 0}^d)$.*

Example. *In the ring $k[u_1, \dots, u_d]$, for each integer $n \geq 1$ the integral closure of the ideal generated by u_1^n, \dots, u_d^n is $(u_1, \dots, u_d)^n$.*

Exercise. *Check that in the preceding subsection, one can in all statements and proofs replace the positive quadrant of \mathbf{R}^d by any strictly convex rational cone*

$\sigma_0 \subset \mathbf{R}^d$ and let \mathcal{M} denote the ideal generated by monomials u^{m^1}, \dots, u^{m^q} of the normal toric algebra $k[\check{\sigma}_0 \cap M]$; its integral closure $\overline{\mathcal{M}}$ in that algebra is generated by the monomials with exponents in the convex hull in $\check{\sigma}_0$ of $\bigcup_{1 \leq s \leq q} (m^s + \check{\sigma}_0)$.



Note that the picture corresponds to a case where the generating system is not minimal.

4 The monomial Briançon-Skoda Theorem

Theorem 4.1. (Carathéodory's Theorem): *Let E be a subset of \mathbf{R}^d ; every point of the convex hull of E is in the convex hull of $d + 1$ points of E .*

Proof. For the reader's convenience, here is a sketch of the proof, according to [Grü]. First one checks that the convex hull of E , defined as the intersection of all convex subsets of \mathbf{R}^d containing E , coincides with the set of points of \mathbf{R}^d which are in the convex hull of a finite number of points of E :

Given a finite set F of points of E , its convex hull \overline{F} is contained in the convex hull \overline{E} of E . Now for two finite sets F and F' we have $\overline{F} \cup \overline{F'} \subseteq \overline{F \cup F'}$, so that $\bigcup_F \overline{F}$ is convex. It contains E and so has to be equal to \overline{E} , which proves the assertion.

Given a point x of the convex hull of E , let p be the smallest integer such that x is in the convex hull of $p + 1$ points of E , i.e., that $x = \sum_{i=0}^p \alpha_i x_i$, with $\alpha_i \geq 0$, $\sum_{i=0}^p \alpha_i = 1$ and $x_i \in E$; we must prove that $p \leq d$. Assume that $p > d$. Then the points x_i must be affinely dependent: there is a relation $\sum_{i=0}^p \beta_i x_i = 0$ with $\beta_i \in \mathbf{R}$, where not all the β_i are zero and $\sum_{i=0}^p \beta_i = 0$. We may choose the β_i so that at least one is > 0 and renumber the points x_i so that $\beta_p > 0$ and for each index i such that $\beta_i > 0$ we have $\frac{\alpha_i}{\beta_i} \geq \frac{\alpha_p}{\beta_p}$. For $0 \leq i \leq p - 1$ set $\gamma_i = \alpha_i - \frac{\alpha_p}{\beta_p} \beta_i$, and $\gamma_p = 0$. Now we have

$$\sum_{i=0}^{p-1} \gamma_i x_i = \sum_{i=0}^p \gamma_i x_i = \sum_{i=0}^p \alpha_i x_i - \frac{\alpha_p}{\beta_p} \sum_{i=0}^p \beta_i x_i = x$$

and moreover

$$\sum_{i=0}^{p-1} \gamma_i = \sum_{i=0}^p \gamma_i = \sum_{i=0}^p \alpha_i - \frac{\alpha_p}{\beta_p} \sum_{i=0}^p \beta_i = 1.$$

Finally each γ_i is indeed ≥ 0 since if $\beta_i \leq 0$ we have $\gamma_i \geq \alpha_i \geq 0$ and if $\beta_i > 0$ and then by our choice of numbering we have $\gamma_i = \beta_i \left(\frac{\alpha_i}{\beta_i} - \frac{\alpha_p}{\beta_p} \right) \geq 0$. Assuming that $p > d$ we have expressed x as the barycenter of the p points x_0, \dots, x_{p-1} of E with coefficients γ_i , which contradicts the definition of p and thus proves the theorem. \circlearrowright

Taking for E the set consisting of $d + 1$ affinely independent points of \mathbf{R}^d shows that the bound of the theorem is optimal. However, the following result means that this is essentially the only case where $d + 1$ points are necessary:

Proposition 4.2. (Fenchel ([F]), Hanner-Rådström ([H-R])) *Let $E \subset \mathbf{R}^d$ be a subset having at most d connected components. Every point of the convex hull of E is in the convex hull of d points of E .*

Proof. (after [H-R]): Assume that a point m of the convex hull is *not* in the convex hull of any subset of d points of E . By Caratheodory's theorem, m is in the convex hull $\tau \subset \mathbf{R}^d$ of $d + 1$ points of E ; if these $d + 1$ points were not linearly independent, the point m would be in the convex hull of the intersection of E with a hyperplane and we could apply Caratheodory's theorem in a space of dimension $d - 1$ and contradict our assumption, so the convex hull τ of the $d + 1$ points is a d -simplex. Let us choose m as origin, and denote by (q_0, \dots, q_d) the vertices of τ . We have therefore $0 = \sum_0^d r_i q_i$ with $r_i \geq 0$ and $\sum_0^d r_i = 1$. Our assumption that 0 is not the barycenter of d points implies that 0 is in the interior of τ , that is, $r_i > 0$ for $0 \leq i \leq d$. Consider the simplex $-\tau$ and the cones with vertex 0 drawn on the faces of $-\tau$. Since the r_i are > 0 , we can reinterpret the expression of 0 as a barycenter of the q_i to mean that each q_i is in the cone with vertex 0 generated by the vectors $-q_j$ for $j \neq i$; thus each of these cones drawn from 0 on the faces of $-\tau$ contains a point of E , namely one of the q_i . The union of their closures is \mathbf{R}^d because $-\tau$ is a d -simplex, and no point of E can be on the boundary of one of these cones; if such was the case, this point,

together with $d - 1$ of the vertices of τ , would define a $(d - 1)$ -simplex with vertices in E and containing 0, a possibility which we have excluded. Therefore these $d + 1$ cones divide E into $d + 1$ disjoint non empty parts, and E must have at least $d + 1$ connected components. \circlearrowright

Now let us remark that, given finitely many points m^1, \dots, m^q in the positive quadrant $\mathbf{R}_{\geq 0}^d$, the set $E = \bigcup_{s=1}^q (m^s + \mathbf{R}_{\geq 0}^d)$ is connected. Indeed, by definition, each point of this set is connected by a line to at least one of the points m^s , and any point of $\mathbf{R}_{\geq 0}^d$ having each of its coordinates larger than the maximum over $s \in \{1, \dots, q\}$ of the corresponding coordinate of the m^s is in E and connected by lines to all the points m^s , so that any two of the points m^s are connected in E .

Now let σ be a strictly convex rational cone in $\check{\mathbf{R}}^d$ and $\check{\sigma} \subset \mathbf{R}^d$ its dual. We need not assume that σ is regular, or even simplicial. Let m^1, \dots, m^q be integral points in $\check{\sigma}$, corresponding to monomials u^{m^1}, \dots, u^{m^q} in the algebra $k[\check{\sigma} \cap M]$. The integral closure $\overline{\mathcal{M}}$ in $k[\check{\sigma} \cap M]$ of the ideal \mathcal{M} generated by the monomials u^{m^s} is the ideal generated by the monomials u^n such that n is in the convex hull of the set $E = \bigcup_{s=1}^q (m^s + \check{\sigma})$. What we have just said about the connectedness of E extends immediately.

Theorem 4.3. (Monomial Briançon-Skoda theorem) *Let k be a field and let σ be a strictly convex rational cone in \mathbf{R}^d . Given a monomial ideal \mathcal{M} in $k[\check{\sigma} \cap M]$, we have the inclusion of ideals*

$$\overline{\mathcal{M}^d} \subset \mathcal{M}.$$

Proof. (Compare with [T3]) Let y_1, \dots, y_N be a system of homogeneous generators of the graded k -algebra $k[\check{\sigma} \cap M]$ and let y^{m^1}, \dots, y^{m^q} be generators of \mathcal{M} in $k[\check{\sigma} \cap M]$. Set $E = \bigcup_{1 \leq s \leq q} (m^s + \check{\sigma}) \subset \check{\sigma}$. Thanks to Proposition 4.2 and the fact that E is connected, it suffices to show that any point $n \in \check{\sigma} \cap M$ which is the barycenter of d points x_1, \dots, x_d , each of which is the sum of d points of E , is in E . But then $\frac{1}{d}n$ is also, as a barycenter of barycenters of points of E , in the convex hull of E , and therefore, by Proposition 4.2, the barycenter of d points of E . Let us write $\frac{1}{d}n = \sum_{i=1}^d r_i e_i$ with $e_i \in E$, $r_i \geq 0$ and $\sum_{i=1}^d r_i = 1$. At least one of the r_i , say r_1 , must be $\geq \frac{1}{d}$, so that $n \in e_1 + \check{\sigma} \subset E$, which proves the result. \circlearrowright

Exercise. *Prove by the same method that for each integer $\lambda \geq 1$ we have*

$$\overline{\mathcal{M}^{d+\lambda-1}} \subset \mathcal{M}^\lambda.$$

Remark. *It is not difficult to check that*

$$\overline{E} = \lim_{n \rightarrow \infty} \frac{nE}{n} = \bigcup_{n \in \mathbf{N}} \frac{nE}{n},$$

where nE means the Minkowski multiple, i.e., set of all sums of n elements of E , while dividing by n meant homothety of ratio $\frac{1}{n}$. In fact, the inclusion

$\bigcup_{n \in \mathbf{N}} \frac{nE}{n} \subset \overline{E}$ is clear, and the first set is also clearly convex, so they are equal. The combinatorial avatar of the weak form of the Briançon-Skoda theorem which states that $x \in \overline{\mathcal{M}} \implies x^d \in \mathcal{M}$ is the existence of a uniform bound for the n such that $x \in \overline{E} \implies nx \in E$, namely $n = d$.

The Briançon-Skoda theorem is the statement $\overline{\mathcal{M}^d} \subset \mathcal{M}$ for an ideal in a d -dimensional regular local ring. The rings $k[\overline{\sigma} \cap M]$ are not regular in general, nor are they local, but the monomial Briançon-Skoda theorem for ideals in their localizations $k[\overline{\sigma} \cap M]_m$ follows from the results of [Li-T] in the case where \mathcal{M} contains an ideal generated by a regular sequence and with the same integral closure, since $k[\overline{\sigma} \cap M]$ has only rational singularities (see [TE]) and hence $k[\overline{\sigma} \cap M]_m$ is a pseudo-rational local ring.

The Briançon-Skoda theorem was originally proved (see [B-S]) by analytic methods for ideals of $\mathbf{C}\{z_1, \dots, z_d\}$ and has been the subject of many algebraic proofs and generalizations. The first algebraic proof was given in [Li-T], albeit for a restricted class of ideals in an extended class of rings (pseudo-rational ones). I refer the reader to Hochster's and Lazarsfeld's lectures in this volume for references and recent developments.

5 Polynomial ideals and non degeneracy

The hypothesis of non degeneracy of a polynomial with respect to its Newton polyhedron has a fairly ancient history in the sense that it was made more or less implicitly by authors trying to compute various invariants of a projective hypersurface from its Newton polyhedron. In the 19th Century one may quote Minding and Elliott, and in the twentieth Baker and Hodge (see [Hod]). The last three were interested in computing the geometric genus of a projective curve or surface with isolated singularities from its Newton polygon or polyhedron. This is a special case of computation of a multiplier ideal (see [M-T], and compare its Theorem of Hodge 2.3.1 with the recent work of J. Howald expounded in Lazarsfeld's lectures in this volume; see also [Ho]).

The modern approach to non degeneracy was initiated essentially by Kushnirenko and Khovanskii who made the non-degeneracy condition explicit and computed from the Newton polyhedron invariants of a similar nature. In particular Khovanskii gave the general form of Hodge's result. The essential facts behind the classical computations turned out to be that non degenerate singularities have embedded toric (pseudo-)resolutions which depend only on their Newton polyhedron and from which one can read combinatorially various interesting invariants, and that in the spaces of coefficients of all those functions or systems of functions having given polyhedra, those which are non-degenerate are Zariski-dense.

Let

$$f = \sum_p f_p u^p$$

be an arbitrary polynomial or power series in d variables with coefficients in the field k . Let $\text{Supp}(f) = \{p \in \mathbf{R}^d / f_p \neq 0\}$ be its *support*. The affine Newton polyhedron of f in the coordinates (u_1, \dots, u_d) is the boundary $\mathcal{N}(f)$ of the convex hull in $\mathbf{R}_{\geq 0}^d$ of the support of f . The local Newton polyhedron is the boundary $\mathcal{N}_+(f)$ of

$$\mathcal{P}_+(f) = \text{convex hull of } (\text{Supp}(f) + \mathbf{R}_{\geq 0}^d).$$

It has finitely many compact faces and its non compact faces of dimension $\leq d-1$ are parallel to coordinate planes (intersections of coordinate hyperplanes). Note that both polyhedra depend not only on f but also on the choice of coordinates. Remark also that the local Newton polyhedron has no interest if the polynomial or series f has a non zero constant term.

We can define the affine (resp. local) support function associated with the function f as follows (in the affine case, it is the same definition as that given above, applied to the set of monomials appearing in f): .

For the affine Newton polyhedron it is the function defined on $\check{\mathbf{R}}^d$ by

$$h_{\mathcal{N}(f)}(\ell) = \min_{p \in \mathcal{N}(f)} \ell(p),$$

and for the local Newton polyhedron it is defined on the first quadrant $\check{\mathbf{R}}_{\geq 0}^d$ by

$$h_{\mathcal{N}_+(f)}(\ell) = \min_{p \in \mathcal{N}_+(f)} \ell(p).$$

Both functions are piecewise linear in their domain of definition, which means that there is a decomposition of their respective domains of definition into convex cones such that the corresponding functions are linear in each cone. These collections of cones are actually fans, in $\check{\mathbf{R}}^d$ and $\check{\mathbf{R}}_{\geq 0}^d$ respectively. These fans are "dual" to the Newton polyhedra in the following sense:

Consider, say for the local polyhedron, the following equivalence relation between linear functions:

$$\ell \equiv \ell' \iff \{p \in \mathcal{N}_+(f) \mid \ell(p) = h_{\mathcal{N}_+(f)}(\ell)\} = \{p \in \mathcal{N}_+(f) \mid \ell'(p) = h_{\mathcal{N}_+(f)}(\ell')\}$$

Then, the equivalence classes form a decomposition of the first quadrant into strictly convex rational cones, and by definition the support function is linear in each of them, given by $\ell \mapsto \ell(p)$ for any p in the set $\{p \in \mathcal{N}_+(f) \mid \ell(p) = h_{\mathcal{N}_+(f)}(\ell)\}$. These sets are *faces* of the Newton polyhedron, and the collection of the cones constitutes a fan $\Sigma_{\mathcal{N}}$ in $\mathbf{R}_{\geq 0}^d$, called the *dual fan* of the Newton polyhedron. This establishes a *one to one decreasing correspondence between the cones (except for the origin) of the dual fan of a Newton polyhedron and the faces of all dimensions of that Newton polyhedron*. Note that the cones corresponding to non compact faces of the Newton polyhedron meet coordinate hyperplanes outside the origin.

We have now associated to each polynomial $f = \sum_p f_p u^p$ a dual fan in $\check{\mathbf{R}}^d$ corresponding to the global Newton polyhedron, and another one in $\check{\mathbf{R}}_{\geq 0}^d$ corresponding to the local Newton polyhedron. The local polyhedron is also defined

for a series $f = \sum_p f_p u^p$, and the combinatorial constructions are the same. Let us for the moment restrict our attention to the local polyhedron, assuming that $f_0 = 0$ and let us choose a regular refinement Σ of the fan associated to it.

By the definition just given, this means that for each cone $\sigma = \langle a^1, \dots, a^k \rangle$ of the fan Σ , the primitive vectors a^i form part of a basis of the integral lattice, and all the linear forms $p \mapsto \langle a^i, p \rangle$, when restricted to the set $\{p/f_p \neq 0\}$, take their minimum value on the same subset, which is a face, of the (local) Newton polyhedron of $f = \sum_p f_p u^p$. This face may or may not be compact.

Let us examine the behavior of f under the map $\pi(\sigma): Z(\sigma) \rightarrow \mathbf{A}^d(k)$ corresponding to a cone $\sigma = \langle a^1, \dots, a^d \rangle \subset \check{\mathbf{R}}_{\geq 0}^d$ of a regular fan which is a subdivision of the fan associated to the local polyhedron of f . We assume that f is not divisible by any of the coordinates. If we write h for $h_{\mathcal{N}_+(f)}$ we get

$$f \circ \pi(\sigma) = \sum_p f_p y_1^{\langle a^1, p \rangle} \dots y_d^{\langle a^d, p \rangle} = y_1^{h(a^1)} \dots y_d^{h(a^d)} \sum_p f_p y_1^{\langle a^1, p \rangle - h(a^1)} \dots y_d^{\langle a^d, p \rangle - h(a^d)}$$

The last sum is by definition the *strict transform* of f by $\pi(\sigma)$.

I leave it as an exercise to check that:

- a) In each chart $Z(\sigma)$ the exceptional divisor consists (set-theoretically) of the union of those hyperplanes $y_j = 0$ such that a^j is not a basis vector of $\check{\mathbf{Z}}^d$.
- b) Provided that no monomial in the u_i divides f , the hypersurface

$$\sum_p f_p y_1^{\langle a^1, p \rangle - h(a^1)} \dots y_d^{\langle a^d, p \rangle - h(a^d)} = 0$$

is indeed the strict transform by the map $\pi(\sigma): Z(\sigma) \rightarrow \mathbf{A}^d(k)$ of the hypersurface $X \subset \mathbf{A}^d(k)$ defined by $f(u_1, \dots, u_d) = 0$, in the sense that it is the closure in $Z(\sigma)$ of the image of $X \cap (k^*)^d$ by the isomorphism induced by $\pi(\sigma)$ on the tori of the two toric varieties $Z(\sigma)$ and $\mathbf{A}^d(k)$ as well as in the sense that it is obtained from $f \circ \pi(\sigma)$ by factoring out as many times as possible the defining functions of the components of the exceptional divisor.

Let us denote by \tilde{f} the strict transform of f and note that by construction it has a non zero constant term: the cone σ is of maximal dimension, which means that there is a unique exponent p such that $\langle a, p \rangle = h(a)$ for $a \in \sigma$. If we consider the map $\pi(\tau)$ associated to a face τ of σ , it coincides with the restriction of $\pi(\sigma)$ to an open set $Z(\tau) \subset Z(\sigma)$ which is of the form $y_j \neq 0$ for $j \in J$ where J depends on $\tau \subset \sigma$.

Now we can, for each cone σ of our regular fan, stratify the space $Z(\sigma)$ in such a way that $\pi(\sigma)^{-1}(0)$ is a union of strata. Let I be a subset of $\{1, 2, \dots, d\}$ and define S_I to be the constructible subset of $Z(\sigma)$ defined by $y_i = 0$ for $i \in I$, $y_i \neq 0$ for $i \notin I$. The S_I for $I \subset \{1, 2, \dots, d\}$ constitute a partition of $Z(\sigma)$ into non singular varieties, constructible in $Z(\sigma)$, which we call the *natural stratification* of $Z(\sigma)$. Note that if we glue up two charts $Z(\sigma)$ and $Z(\sigma')$ along $Z(\sigma \cap \sigma')$, the natural stratifications glue up as well.

If we restrict the strict transform

$$\tilde{f}(y_1, \dots, y_d) = \sum_p f_p y_1^{\langle a^1, p \rangle - h(a^1)} \dots y_d^{\langle a^d, p \rangle - h(a^d)}$$

to a stratum S_I , we see that in the sum representing $\tilde{f}(y_1, \dots, y_d)$ only the terms $f_p y_1^{\langle a^1, p \rangle - h(a^1)} \dots y_d^{\langle a^d, p \rangle - h(a^d)}$ such that $\langle a^i, p \rangle - h(a^i) = 0$ for $i \in I$ survive. These equalities define a unique face γ_I of the Newton polyhedron of f , since our fan is a subdivision of its dual fan. Given a series $f = \sum_p f_p u^p$ and a weight vector $\tilde{a} \in \mathbf{R}_{\geq 0}^d$, the set $\{p \in \mathbf{Z}_{\geq 0}^d / f_p \neq 0 \text{ and } \langle \tilde{a}, p \rangle = h(\tilde{a})\}$ is a face of the local Newton polyhedron of f , corresponding to the cone of the dual fan which contains \tilde{a} in its relative interior. If all the coordinates of the vector \tilde{a} are positive, this face is compact.

Moreover, if we define

$$f_{\gamma_I} = \sum_{p \in \gamma_I} f_p u^p$$

to be the partial polynomial associated to the face γ_I , which is nothing but the sum of the terms of f whose exponent is in the face γ_I , we see that we have the fundamental equality

$$\tilde{f}|_{S_I} = \widetilde{f_{\gamma_I}}|_{S_I}$$

and we remark moreover that $\widetilde{f_{\gamma_I}}$ is a function on $Z(\sigma)$ which is independent of the coordinates y_i for $i \in I$, so that it is determined by its restriction to S_I .

Now, to say that the strict transform $\tilde{f} = 0$ in $Z(\sigma)$ of the hypersurface $f = 0$ is transversal to the stratum S_I and is non singular in a neighborhood of its intersection with it is equivalent to saying that the restriction $\tilde{f}|_{S_I}$ of the function \tilde{f} defines, by the equation $\tilde{f}|_{S_I} = 0$, a non singular hypersurface of S_I . By the definition of S_I and what we have just seen, this in turn is equivalent to saying that the equation $\widetilde{f_{\gamma_I}} = 0$ defines a non singular hypersurface in the torus $(k^*)^d = \{u / \prod_1^d u_j \neq 0\}$ of $Z(\sigma)$, and this finally is equivalent to saying that $f_{\gamma_I} = 0$ defines a non singular hypersurface in the torus $(k^*)^d$ of the affine space $\mathbf{A}^d(k)$ since $\pi(\sigma)$ induces an isomorphism of the two tori.

This motivates the definition:

Definition. *The series $f = \sum_p f_p u^p$ is non degenerate with respect to its Newton polyhedron in the coordinates (u_1, \dots, u_d) if for every compact face γ of $\mathcal{N}_+(f)$ the polynomial f_γ defines a non singular hypersurface of the torus $(k^*)^d$.*

Remark. *By definition of the faces of the Newton polyhedron and of the dual fan, in each chart $Z(\sigma)$ of a regular fan refining the dual fan of $\mathcal{N}_+(f)$, the compact faces γ_I correspond to strata S_I of the canonical stratification which are contained in $\pi(\sigma)^{-1}(0)$. Each stratum S_I which is not contained in $\pi(\sigma)^{-1}(0)$ contains in its closure strata which are.*

Proposition 5.1. *If the germ of hypersurface X is defined by the vanishing of a series f which is non-degenerate, there is a neighborhood U of 0 in $\mathbf{A}^d(k)$ (a formal neighborhood if the series f does not converge) such that the strict*

transform of $X \cap U$ by the toric map $\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$ associated to a regular fan refining the dual fan of its Newton polyhedron is non singular and transversal in each chart to the strata of the canonical stratification.

Proof. By the fundamental equality seen above, the restriction of the strict transform to one of the strata contained in $\pi(\sigma)^{-1}(0)$, say S_I , has the same behavior as the restriction of f_{γ_I} , where γ_I is a compact face of the Newton polyhedron of f , to the torus $(k^*)^d$. As we saw, this implies that the strict transform of $X \cap U$ is non singular and transversal to S_I . By openness of transversality the same transversality holds, within a neighborhood of each point of $\pi(\Sigma)^{-1}(0)$, for all strata.

Since the map $\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$ is proper, there is a neighborhood U of 0 in $\mathbf{A}^d(k)$ such that the strict transform by $\pi(\Sigma)$ of the hypersurface $X \subset \mathbf{A}^d(k)$ is non singular in $\pi(\Sigma)^{-1}(U)$ and transversal in each chart $Z(\sigma)$ to all the strata of the canonical stratification. \circlearrowright

The definition and properties of non degeneracy extend to systems of functions as follows:

Let f_1, \dots, f_k be series in the variables u_1, \dots, u_d defining a subspace $X \subset \mathbf{A}^d(k)$ in a neighborhood of 0. For each $j = 1, \dots, k$ we have a local Newton polyhedron $\mathcal{N}_+(f_j)$. Let us choose a regular fan Σ of $\mathbf{R}_{\geq 0}^d$ compatible with all the fans dual to the polyhedra $\mathcal{N}_+(f_j)$ for $j = 1, \dots, k$. We have for each j the same correspondence as above between the strata S_I of each chart $Z(\sigma)$ for $\sigma \in \Sigma$ and the faces of $\mathcal{N}_+(f_j)$, the strata contained in $\pi(\sigma)^{-1}(0)$ corresponding to compact faces.

For each vector $\check{a} \in \check{\mathbf{R}}_{>0}^d$ we get as above a system of equations $f_{1,\check{a}}, \dots, f_{k,\check{a}}$ where $f_{j,\check{a}} = \sum_{\{p/\langle \check{a}, p \rangle = h(\check{a})\}} f_{j,p} u^p$.

Definition. *The system of equations f_1, \dots, f_k is said to be non degenerate of rank c with respect to the Newton polyhedra of the f_j in the coordinates (u_1, \dots, u_d) if no coordinate is a zero divisor modulo the ideal generated by f_1, \dots, f_k and for each vector $\check{a} \in \check{\mathbf{R}}_{>0}^d$ the ideal of $k[u_1^{\pm 1}, \dots, u_d^{\pm 1}]$ generated by the polynomials $f_{1,\check{a}}, \dots, f_{k,\check{a}}$ defines a non singular subvariety of dimension $d - c$ of the torus $(k^*)^d$.*

Remark. *The non degeneracy condition does not in general imply that for each choice of a compact face γ_j in each $\mathcal{N}_+(f_j)$, the ideal generated by the polynomials $f_{1\gamma_1}, \dots, f_{k\gamma_k}$ defines a non singular subvariety of dimension $d - c$ of the torus $(k^*)^d$. One can interpret this in terms of the positions of the strict transforms of the f_j after a desingularizing toric map as in the next proposition.*

Exactly as in the case of hypersurfaces, one then has the

Proposition 5.2. *If the system of equations f_1, \dots, f_k is non degenerate of rank c , for any regular fan Σ of $\mathbf{R}_{\geq 0}^d$ compatible with the dual fans of the polyhedra $\mathcal{N}_+(f_j)$, there is a neighborhood U of 0 in $\mathbf{A}^d(k)$ (a formal neighborhood if all the series f_j do not converge) such that the strict transform $X' \subset Z(\Sigma)$ by the*

toric map $\pi(\Sigma): Z(\Sigma) \rightarrow \mathbf{A}^d(k)$ of the subvariety $X \cap U$ defined in U by the ideal generated by f_1, \dots, f_k is non singular and of dimension $d - c$ and transversal to the strata of the natural stratification in $\pi(\Sigma)^{-1}(U)$.

The proof is the same as that of Proposition 5.1.

There is a difference, however, between the birational map $X' \rightarrow X \cap U$ induced by $\pi(\Sigma)$ and a resolution of singularities; this map is not necessarily an isomorphism outside of the singular locus; it is therefore only a *pseudo-resolution* in the sense of [G-T]. In fact, even in the non degenerate case, and even for a hypersurface, the Newton polyhedron contains in general far too little information about the singular locus of X near 0. Kushnirenko introduced, for isolated hypersurface singularities, the notion of being *convenient* with respect to a coordinate system. It means that the Newton polyhedron meets all the coordinate axis of $\mathbf{R}_{\geq 0}^d$. For a hypersurface with isolated singularity, it implies that a toric pseudo-resolution associated to the Newton polyhedron is a resolution. This was extended and generalized by M. Oka for complete intersections. The reader is referred to ([Ok], Chap. III, especially Theorem 3.4) and we will only quote here the following fact which is also a consequence of the existence of a toric pseudo-resolution (see [Ok], Chap. III, Lemma 2.2):

If k is a field and $(X, 0) \subset \mathbf{A}^d(k)$ is a germ of a complete intersection with equations $f_1 = \dots = f_c = 0$, which is non degenerate with respect to the Newton polyhedra of its equations in the coordinates u_1, \dots, u_d , then there is a (possibly formal) neighborhood U of $0 \in \mathbf{A}^d(k)$ such that the intersection of X and the torus $(k^)^d$ has no singularities in U .*

In the formal case this should be understood as saying that formal germ at 0 of the singular locus of X is contained in the union of the coordinate hyperplanes.

Finally, it seems that the following coordinate-free definition of non degeneracy is appropriate:

Definition. *An algebraic or formal subscheme X of an affine space $\mathbf{A}^d(k)$ is non degenerate at a point $x \in X$ if there exist local coordinates u_1, \dots, u_d centered at x and an open (étale or formal) neighborhood U of x in $\mathbf{A}^d(k)$ such that there is a proper birational toric map $\pi: Z \rightarrow U$ in the coordinates u_1, \dots, u_d with Z non singular and such that the strict transform X' of $X \cap U$ by π is non singular and transversal to the exceptional divisor at every point of $\pi^{-1}(x) \cap X'$.*

If X admits a system of equations which in some coordinates is non degenerate with respect to its Newton polyhedra, it is also non degenerate in this sense as we saw. The converse will not be discussed here.

Then one can state the:

Question (see [T2]) Given a reduced and equidimensional algebraic or formal space X over an algebraically closed field k , is it true that for every point $x \in X$ there is a local formal embedding of X into an affine space $\mathbf{A}^N(k)$ such that X is non degenerate in $\mathbf{A}^N(k)$ at the point x ?

A subsequent problem is to give a geometric interpretation of the systems of coordinates in which an embedded toric resolution for X exists.

For branches (analytically irreducible curve singularities), the question is answered positively, and the problem settled in section 7 below. Recent work of P. González Pérez ([GP]) also settles question and problem for irreducible quasi-ordinary hypersurface singularities.

In [T2] one finds an approach to the simpler problem where the non degeneracy is requested only with respect to a valuation of the local ring of X at x .

In a given coordinate system, and for given Newton polyhedra, “almost all” systems of polynomials having these given Newton polyhedra are non degenerate with respect to them. In this sense there are many non degenerate singularities. However, the non degenerate singularities are very special from the viewpoint of the classification of singularities. A plane complex branch is non degenerate in some coordinate system if and only if it has only one characteristic pair, which means that its equation can be written in some coordinate system

$$u_1^p - u_0^q + \sum_{\frac{i}{q} + \frac{j}{p} > 1} a_{ij} u_0^i u_1^j = 0,$$

with $a_{ij} \in k$, and the integers p, q are coprime. The curve

$$(u_1^2 - u_0^3)^2 - u_0^5 u_1 = 0$$

is degenerate in any coordinate system since it has two characteristic pairs (see [Sm], [B-K]) .

6 Resolution of binomial varieties

This section presents what is in a sense the simplest class of non degenerate singularities, according to the results in [GP-T]:

Let k be a field. Binomial varieties over k are irreducible varieties of the affine space $\mathbf{A}^d(k)$ which can, in a suitable coordinate system, be defined by the vanishing of binomials in these coordinates i.e., expressions of the form $u^m - \lambda_{mn} u^n$ with $\lambda_{mn} \in k^*$. An ideal generated by such binomial expressions is called a *binomial ideal*. These affine varieties defined by prime binomial ideals are also (see [St]) the irreducible affine varieties on which a torus of the same dimension acts algebraically with a dense orbit; they are the (not necessarily normal) *affine toric varieties*.

Binomial ideals were studied in [E-S]; Eisenbud and Sturmfels showed in particular that if k is algebraically closed their geometry is determined by the lattice generated by the differences $m - n$ of the exponents of the generating binomials. If the field k is not algebraically closed, the study becomes more complicated. Here I will assume throughout that k is algebraically closed. It is natural to study the behavior of binomial ideals under toric maps.

Let $\sigma = \langle a^1, \dots, a^d \rangle$ be a regular cone in $\check{\mathbf{R}}_{\geq 0}^d$. The image of a binomial $u^m - \lambda_{mn}u^n$ by the map $k[u_1, \dots, u_d] \rightarrow k[y_1, \dots, y_d]$ determined by $u_i \mapsto y_1^{a_i^1} \dots y_d^{a_i^d}$ is given by:

$$u^m - \lambda_{mn}u^n \mapsto y_1^{\langle a^1, m \rangle} \dots y_d^{\langle a^d, m \rangle} - \lambda_{mn} y_1^{\langle a^1, n \rangle} \dots y_d^{\langle a^d, n \rangle}.$$

In general this only tells us that the transform of a binomial is a binomial, which is no news since by definition of a toric map the transform of a monomial is a monomial.

However, something interesting happens if we assume that the cone σ is *compatible* with the hyperplane H_{m-n} which is the dual in the space of weights of the vector $m-n$ of the space of exponents, in the sense of definition 2, where we remember that the origin $\{0\}$ is a face of any polyhedral cone. Note that the Newton polyhedron of a binomial has only one compact face, which is a segment, so that for a cone in $\check{\mathbf{R}}_{\geq 0}^d$, being compatible with the hyperplane H_{m-n} is the same as being compatible with the dual fan of the Newton polyhedron of our binomial.

Let us assume that the binomial hypersurface $u^m - \lambda_{mn}u^n = 0$ is irreducible; this means that no variable u_j appears in both monomials, and the vector $m-n$ is primitive. In the sequel, I will tacitly assume this and also that our binomial is really singular, i.e., not of the form $u_1 - \lambda u^m$.

If the convex cone σ of dimension d is compatible with the hyperplane H_{m-n} , it is contained in one of the closed half-spaces determined by H_{m-n} . This means that all the non zero $\langle a^i, m-n \rangle$ have the same sign, say positive. It also means that, if we renumber the vectors a^i in such a way that $\langle a^i, m-n \rangle = 0$ for $1 \leq i \leq t$ and $\langle a^i, m-n \rangle > 0$ for $t+1 \leq i \leq d$, we can write the transform of our binomial in the following way:

$$u^m - \lambda_{mn}u^n \mapsto y_1^{\langle a^1, n \rangle} \dots y_d^{\langle a^d, n \rangle} (y_{t+1}^{\langle a^{t+1}, m-n \rangle} \dots y_d^{\langle a^d, m-n \rangle} - \lambda_{mn}).$$

And we can see that the strict transform $y_{t+1}^{\langle a^{t+1}, m-n \rangle} \dots y_d^{\langle a^d, m-n \rangle} - \lambda_{mn} = 0$ of our hypersurface in the chart $Z(\sigma)$ is non singular!

It is also irreducible in view of the results of [E-S] because we assumed that the vector $m-n$ is primitive and the matrix (a_j^i) is unimodular. This implies that the vector $(0, \dots, 0, \langle a^{t+1}, m-n \rangle, \dots, \langle a^d, m-n \rangle)$ is also primitive, and the strict transform irreducible. Moreover, in the chart $Z(\sigma)$ with $\sigma = \langle a^1, \dots, a^d \rangle$, the strict transform meets the hyperplane $y_j = 0$ if and only if $\langle a^j, m-n \rangle = 0$. Unless our binomial is non singular, a case we excluded, this implies that a^j is not a vector of the canonical basis of W , so that $y_j = 0$ is a component of the exceptional divisor. So we see that the strict transform meets the exceptional divisor only in those charts such that $\sigma \cap H_{m-n} \neq \{0\}$, and then meets it transversally.

So we have in this very special case achieved that the total transform of our irreducible binomial hypersurface defines in each chart a *divisor with normal crossings* that is, a divisor locally at every point defined in suitable local coordinates by the vanishing of a monomial and whose irreducible components are non singular.

Now let us consider a prime binomial ideal of $k[u_1, \dots, u_d]$ generated by $(u^{m^\ell} - \lambda_\ell u^{n^\ell})_{\ell \in \{1, \dots, L\}}$, $\lambda_\ell \in k^*$. Let us denote by \mathcal{L} the sublattice of \mathbf{Z}^d generated by the differences $m^\ell - n^\ell$. According to [E-S], the dimension of the subvariety $X \subset \mathbf{A}^d(k)$ defined by the ideal is $d - r$ where r is the rank of the \mathbf{Q} -vector space $\mathcal{L} \otimes_{\mathbf{Z}} \mathbf{Q}$. To each binomial is associated a hyperplane $H_\ell \subset \check{\mathbf{R}}^d$, the dual of the vector $m^\ell - n^\ell \in \mathbf{R}^d$. The intersection \mathcal{W} of the hyperplanes H_ℓ is the dual of the vector subspace $\mathcal{L} \otimes_{\mathbf{Z}} \mathbf{R}$ of \mathbf{R}^d generated by the vectors $m^\ell - n^\ell$; its dimension is $d - r$.

Let Σ be a fan with support $\mathbf{R}_{\geq 0}^d$ which is compatible with each of the hyperplanes H_ℓ . Let us compute the transforms of the generators $u^{m^\ell} - \lambda_\ell u^{n^\ell}$ in a chart $Z(\sigma)$ associated to the cone $\sigma = \langle a^1, \dots, a^d \rangle$: after renumbering the vectors a^j and possibly exchanging some m^ℓ, n^ℓ and replacing λ_ℓ by its inverse, we may assume that a^1, \dots, a^t are in \mathcal{W} , that the $\langle a^j, m^\ell - n^\ell \rangle$ are ≥ 0 for $j = t + 1, \dots, d$, and that moreover for each such index j there is an ℓ such $\langle a^j, m^\ell - n^\ell \rangle > 0$. The transforms of the binomials can be written

$$y_1^{\langle a^1, n^\ell \rangle} \dots y_d^{\langle a^d, n^\ell \rangle} (y_{t+1}^{\langle a^{t+1}, m^\ell - n^\ell \rangle} \dots y_d^{\langle a^d, m^\ell - n^\ell \rangle} - \lambda_\ell)$$

with that additional condition. If $\sigma \cap \mathcal{W} = \{0\}$, we have $t = 0$ and the subvariety defined by the equations just written (the strict transform of X in $Z(\sigma)$) does not meet any coordinate hyperplane; in particular it does not meet the exceptional divisor. In general, still assuming that none of the binomials is already in the form $u_j - \lambda$, one sees that the additional condition implies that, just like in the case of hypersurfaces, the strict transform meets the hyperplane $y_j = 0$ if and only if a^j is in \mathcal{W} .

Now the claim is that in each chart $Z(\sigma)$ the strict transform is either empty or non singular and transversal to the exceptional divisor.

The \mathbf{Q} -vector space generated by the $m^\ell - n^\ell$ is of dimension r . Let us assume that $m^1 - n^1, \dots, m^r - n^r$ generate it and let us denote by \mathcal{L}_1 the lattice which they generate in \mathbf{Z}^d . By construction, the quotient $\mathcal{L}/\mathcal{L}_1$ is a torsion \mathbf{Z} -module. Let us first show that the strict transform of the subspace $X_1 \subset X$ defined by the first r binomial equations is non singular and transversal to the exceptional divisor.

We consider then, for each cone $\sigma = \langle a^1, \dots, a^d \rangle$, the equations

$$\begin{aligned} y_1^{\langle a^1, m^1 - n^1 \rangle} \dots y_d^{\langle a^d, m^1 - n^1 \rangle} - \lambda_1 &= 0 \\ y_1^{\langle a^1, m^2 - n^2 \rangle} \dots y_d^{\langle a^d, m^2 - n^2 \rangle} - \lambda_2 &= 0 \\ &\vdots \\ y_1^{\langle a^1, m^r - n^r \rangle} \dots y_d^{\langle a^d, m^r - n^r \rangle} - \lambda_r &= 0 \end{aligned}$$

of the strict transform of X_1 in $Z(\sigma)$.

We can compute by logarithmic differentiation their jacobian matrix J , and find with the same definition of t as above an equality of $d \times r$ matrices:

$$y_{t+1} \dots y_d J = y_{t+1}^{\sum_s \langle a^{t+1}, m^s - n^s \rangle} \dots y_d^{\sum_s \langle a^d, m^s - n^s \rangle} (\langle a^j, m^s - n^s \rangle)_{1 \leq j \leq d, 1 \leq s \leq r}.$$

Lemma 6.1. *Given an irreducible binomial variety $X \subset \mathbf{A}^d(k)$, with the notations just introduced, for any regular cone $\sigma = \langle a^1, \dots, a^d \rangle$ compatible with the hyperplanes H_ℓ , the rank of the image in $\text{Mat}_{d \times L}(k)$ of the matrix $(\langle a^j, m^s - n^s \rangle)_{1 \leq j \leq d, 1 \leq s \leq L} \in \text{Mat}_{d \times L}(\mathbf{Z})$ is r .*

Proof. Since the vectors a^j form a basis of \mathbf{Q}^d , and the space $\check{W} = \mathcal{L} \otimes_{\mathbf{Z}} \mathbf{R}$ generated by the $m^s - n^s$ is of dimension r , the rank of the matrix $(\langle a^j, m^s - n^s \rangle)$ is r , which proves the lemma if k is of characteristic zero. If the field k is of positive characteristic the proof is a little less direct; it can be found in [T 2], Chap. 6. Note that in particular the rank of the image in $\text{Mat}_{d \times r}(k)$ of the matrix $(\langle a^j, m^s - n^s \rangle)_{1 \leq j \leq d, 1 \leq s \leq r} \in \text{Mat}_{d \times r}(\mathbf{Z})$ is r . \circlearrowright

Lemma 6.2. *The strict transform X'_1 by $\pi(\Sigma)$ of the subspace $X \subset \mathbf{A}^d(k)$ defined by the ideal of $k[u_1, \dots, u_d]$ generated by the binomials $u^{m^1} - \lambda_1 u^{n^1}, \dots, u^{m^r} - \lambda_r u^{n^r}$ is regular and transversal to the exceptional divisor.*

Proof. Let σ be a cone of maximal dimension in the fan Σ . First note that, in the chart $Z(\sigma)$, none of the coordinates y_{t+1}, \dots, y_d vanishes on the strict transform X'_1 of X_1 and that the equations of X'_1 in $Z(\sigma)$ are independent of y_1, \dots, y_t . Therefore to prove that the jacobian J of the equations has rank r at each point of this strict transform it suffices to show that the rank of the image in $\text{Mat}_{d \times L}(k)$ of the matrix $(\langle a^j, m^s - n^s \rangle)_{1 \leq j \leq d, s \in L} \in \text{Mat}_{d \times L}(\mathbf{Z})$ is r , which follows from the previous lemma. \circlearrowright

Proposition 6.3. *The strict transform X' by $\pi(\Sigma)$ of the subspace $X \subset \mathbf{A}^d(k)$ defined by the ideal of $k[u_1, \dots, u_d]$ generated by the $(u^{m^\ell} - \lambda_\ell u^{n^\ell})_{\ell \in \{1, \dots, L\}}$ is regular and transversal to the exceptional divisor; it is also irreducible in each chart.*

Proof. The preceding discussion shows that the rank of J is r everywhere on the strict transform of X , and by Zariski's jacobian criterion this strict transform is smooth and transversal to the exceptional divisor. Note however that it is not necessarily irreducible; let us show that the strict transform of our binomial variety is one of its irreducible components. Since the differences of the exponents in the total transform and the strict transform of a binomial are the same, the lattice of exponents generated by the exponents of all the strict transforms of the binomials $(u^{m^\ell} - \lambda_{mn} u^{n^\ell})_{\ell \in \{1, \dots, L\}}$ is the image $M(\sigma)\mathcal{L}$ of the lattice \mathcal{L} by the linear map $\mathbf{Z}^d \rightarrow \mathbf{Z}^d$ corresponding to the matrix $M(\sigma)$ with rows (a^1, \dots, a^d) . Similarly the exponents of the strict transforms of $u^{m^1} - \lambda_{m^1 n^1} u^{n^1}, \dots, u^{m^r} - \lambda_{m^r n^r} u^{n^r}$ generate the lattice $M(\sigma)\mathcal{L}_1$. The lattice $M(\sigma)\mathcal{L}$ is the saturation of $M(\sigma)\mathcal{L}_1$, and so according to [E-S], since we assume that k is algebraically closed, the strict transform of our binomial variety is one of the irreducible components of the binomial variety defined by the r equations displayed above.

The charts corresponding to regular cones $\sigma \in \Sigma$ of dimension $< d$ are open subsets of those which we have just studied, so they contribute nothing new. \circlearrowright

In the case of binomial varieties one can show that the regular refinement Σ of the fan Σ_0 determined by the hyperplanes $H_{m^s-n^s}$ can be chosen in such a way that the restriction $X' \rightarrow X$ of the map $\pi(\Sigma)$ to the strict transform X' of X induces an isomorphism outside of the singular locus of X ; it is therefore an embedded resolution of $X \subset \mathbf{A}^d(k)$ and not only a pseudo-resolution; see [GP-T] and [T2], §6.2.

Remark. *Since Hironaka’s 1964 paper ([H]), one usually seeks to achieve resolution of singularities by successions of blowing-ups with non singular centers, which moreover are “permissible”. According to [DC-P], toric maps are dominated by finite successions of blowing-ups with non singular centers.*

Now in view of the results of section 5, we expect that if we deform a binomial variety by adding to each of its equations terms which do not affect the Newton polyhedron, the same toric map will resolve the deformed variety as well. However, it may be only a pseudo-resolution, since the effect of the deformation on the singular locus is difficult to control. The next section shows that in a special case one can, conversely, present a singularity as a deformation of a toric variety, and thus obtain an embedded toric resolution.

7 Resolution of singularities of branches

This section is essentially an exposition of material in [G-T] and [T2]. The idea is to show that any analytically irreducible germ of curve is in a canonical way a deformation of a *monomial* curve, which is defined by *binomial* equations. In this terminological mishap, the *monomial* refers to the parametric presentation of the curve; the parametric presentation is more classical, but the binomial character of the equations is more suitable for resolution of singularities.

The deformation from the monomial curve to the curve is “equisingular”, so that the toric map which resolves the singularities of the monomial curve according to section 6 also resolves the singularities of our original curve once it is suitably embedded in the affine space where the monomial curve embeds. One interpretation of this is that *after a suitable re-embedding, any analytically irreducible curve becomes non-degenerate.*

For example, in order to resolve the singularities at the origin of the plane curve C with equation

$$(u_1^2 - u_0^3)^2 - u_0^5 u_1 = 0,$$

a good method is to view it as the fiber for $v = 1$ of the family of curves in $\mathbf{A}^3(k)$ defined by the equations

$$\begin{aligned} u_1^2 - u_0^3 - v u_2 &= 0 \\ u_2^2 - u_0^5 u_1 &= 0 \end{aligned}$$

as one can see by eliminating u_2 between the two equations. The advantage is that the fiber for $v = 0$ is a binomial variety, which we know how to resolve, and its resolution also resolves all the fibers C_v . For $v \neq 0$, the fiber C_v is

isomorphic to our original plane curve C , re-embedded in $\mathbf{A}^3(k)$ by the functions $u_0, u_1, u_1^2 - u_0^3$.

In more algebraic terms, it gives this:

Let R be a one dimensional excellent equicharacteristic local ring whose completion is an integral domain and whose residue field is algebraically closed. A basic example is $R = k[[x, y]]/(f)$ where k is algebraically closed and $f(x, y)$ is irreducible in $k[[x, y]]$. Then the normalization \bar{R} of R is a (discrete) valuation ring because it is a one dimensional normal local ring. The maximal ideal of \bar{R} is generated by a single element, say t , and each non zero element of \bar{R} can be written uniquely as ut^n , where u is invertible in \bar{R} and $n \in \mathbf{N} \cup \{0\}$. The valuation $\nu(ut^n)$ of that element is n .

In our basic example, the inclusion $R \subset \bar{R}$ is $k[[x, y]]/(f) \subset k[[t]]$ given by $x \mapsto x(t)$, $y \mapsto y(t)$ where $x(t), y(t)$ is a parametrization of the plane curve with equation $f(x, y) = 0$.

Since R is a subalgebra of \bar{R} , the values taken by the valuation on the elements of R (except 0) form a semigroup Γ contained in \mathbf{N} . This semigroup has a finite complement in \mathbf{N} and is finitely generated. Let us write it

$$\Gamma = \langle \gamma_0, \gamma_1, \dots, \gamma_g \rangle.$$

The powers of the maximal ideal of \bar{R} form a filtration

$$\bar{R} \supset t\bar{R} \supset t^2\bar{R} \supset \dots \supset t^n\bar{R} \supset \dots$$

whose associated graded ring

$$\text{gr}_\nu \bar{R} = \bigoplus_{n \in \mathbf{N} \cup \{0\}} t^n \bar{R} / t^{n+1} \bar{R}$$

is a k -algebra isomorphic to the polynomial ring $k[t]$ by the map $t \pmod{t^2\bar{R}} \mapsto t$.

This filtration induces a filtration on the ring R itself, by the ideals $\mathcal{P}_n = R \cap t^n \bar{R}$, and one defines the corresponding associated graded ring

$$\text{gr}_\nu R = \bigoplus_{n \in \mathbf{N} \cup \{0\}} \mathcal{P}_n / \mathcal{P}_{n+1} \subseteq \text{gr}_\nu \bar{R} = k[t].$$

Proposition 7.1. (see [G-T]) *The subalgebra $\text{gr}_\nu R$ of $k[t]$ is equal to the subalgebra generated by $t^{\gamma_0}, t^{\gamma_1}, \dots, t^{\gamma_g}$. It is the semigroup algebra over k of the semigroup Γ of the valuation ν on R ; it is also the affine algebra of the monomial curve in the affine space $\mathbf{A}^{g+1}(k)$ described parametrically by $u_i = t^{\gamma_i}$ for $0 \leq i \leq g$.*

There is a precise geometrical relationship between the original curve C with algebra R and the monomial curve C^Γ with algebra $\text{gr}_\nu R$: according to a general principle of algebra, the ring R is a deformation of its associated graded ring. More precisely, let us assume that R contain a field of representatives of its

residue field k , i.e., that we have a subfield $k \subset R$ such that the composed map $k \subset R \rightarrow R/m = k$ is the identity. This will be the case in particular, according to Cohen's theorem, if the local ring R is complete (and equicharacteristic of course).

Start from the filtration by the ideals \mathcal{P}_n introduced above, set $\mathcal{P}_n = R$ for $n \leq 0$ and consider the algebra

$$\mathcal{A}_\nu(R) = \bigoplus_{n \in \mathbf{Z}} \mathcal{P}_n v^{-n} \subset R[v, v^{-1}].$$

It can be shown (see [T2]) that it is generated as a $R[v]$ -algebra by the $\xi_i v^{-i}$, $0 \leq i \leq g$ where $\xi_i \in R$ is of t -adic order γ_i . Since $\mathcal{P}_n = R$ for $n \leq 0$ it contains as a graded subalgebra the polynomial algebra $R[v]$, and therefore also $k[v]$.

Proposition 7.2. (see [T1], [B], Chap. VIII, exercice 2 for §6; see also [G1] and [G2])

- a) The composed map $k[v] \rightarrow \mathcal{A}_\nu(R)$ is faithfully flat.
- b) The map

$$\sum x_n v^{-n} \mapsto \sum \bar{x}_n,$$

where \bar{x}_n is the image of x_n in the quotient $\mathcal{P}_n/\mathcal{P}_{n+1}$, induces an isomorphism

$$\mathcal{A}_\nu(R)/v\mathcal{A}_\nu(R) \rightarrow \text{gr}_\nu R.$$

- c) For any $v_0 \in k^*$ the map

$$\sum x_n v^{-n} \mapsto \sum x_n v_0^{-n}$$

induces an isomorphism of k -algebras

$$\mathcal{A}_\nu(R)/(v - v_0)\mathcal{A}_\nu(R) \rightarrow R.$$

Proof. Since $k[v]$ is a principal ideal domain, to prove a) it suffices (see [B], Chap. I, §3, No. 1) to prove that $\mathcal{A}_\nu(R)$ has no torsion as a $k[v]$ -module and that for any $v_0 \in k$ we have $(v - v_0)\mathcal{A}_\nu(R) \neq \mathcal{A}_\nu(R)$. The second statement follows from b) and c) which are easy to verify, and the first follows from the fact that $\mathcal{A}_\nu(R)$ is a subalgebra of $R[v, v^{-1}]$. \circlearrowright

This proposition means that there is a one parameter flat family of algebras whose special fiber is the graded algebra and all other fibers are isomorphic to R . Geometrically, this gives us a flat family of curves whose special fiber is the monomial curve and all other fibers are isomorphic to our given curve. This deformation can be realized in the following way. I assume for simplicity that R is complete. Then by definition of the semigroup Γ there are elements $\xi_0(t), \dots, \xi_g(t)$ in $k[[t]]$ which belong to R and are such that their t -adic valuations are the generators γ_i of the semigroup Γ . We may write

$\xi_i(t) = t^{\gamma_i} + \sum_{j>\gamma_i} b_{ij}t^j$ with $b_{ij} \in k$. Let us now introduce a parameter v and consider the family of parametrized curves in $\mathbf{A}^{g+1}(k)$ described as follows:

$$\begin{aligned} u_0 &= \xi_0(vt)v^{-\gamma_0} = t^{\gamma_0} + \sum_{j>\gamma_0} b_{0j}v^{j-\gamma_0}t^j \\ u_1 &= \xi_1(vt)v^{-\gamma_1} = t^{\gamma_1} + \sum_{j>\gamma_1} b_{1j}v^{j-\gamma_1}t^j \\ &\vdots \\ u_g &= \xi_g(vt)v^{-\gamma_g} = t^{\gamma_g} + \sum_{j>\gamma_g} b_{gj}v^{j-\gamma_g}t^j \end{aligned}$$

The parametrization shows that for $v = 0$ we obtain the monomial curve, and for any $v \neq 0$ a curve isomorphic to our given curve, as embedded in $\mathbf{A}^{g+1}(k)$ by the functions ξ_0, \dots, ξ_g . This is a realisation of the family of Proposition 7.2. In order to get an equational representation of that family, we must begin by finding the equations of the monomial curve, which we will then proceed to deform.

The equations of the monomial curve C^Γ correspond to the relations between the generators γ_i of Γ . They are fairly simple in the case where Γ is the semigroup of a plane branch, and in that case C^Γ is a complete intersection. The general setup is as follows:

Consider the \mathbf{Z} -linear map $w: \mathbf{Z}^{g+1} \rightarrow \mathbf{Z}$ determined by sending the i -th base vector e_i to γ_i ; the image of $\mathbf{Z}_{\geq 0}^{g+1}$ is Γ . It is not difficult to see that the kernel of w is generated by differences $m - m'$, where $m, m' \in \mathbf{Z}_{\geq 0}^{g+1}$ and $w(m) = w(m')$. The kernel of w is a lattice (free sub \mathbf{Z} -module) \mathcal{L} in \mathbf{Z}^{g+1} , which must be finitely generated because \mathbf{Z}^{g+1} is a noetherian \mathbf{Z} -module and \mathbf{Z} is a principal ideal domain.

If we choose a basis $m^1 - n^1, \dots, m^g - n^g$ for \mathcal{L} , such that all the m^j, n^j are in $\mathbf{Z}_{\geq 0}^{g+1}$, then it follows from the very construction of semigroup algebras that C^Γ is defined in the space $\mathbf{A}^{g+1}(k)$ with coordinates u_0, \dots, u_g by the vanishing of the binomials $u^{m^1} - u^{n^1}, \dots, u^{m^g} - u^{n^g}$.

Now the faithful flatness of the family of Proposition 7.2 implies that it can be defined in $\mathbf{A}^1(k) \times \mathbf{A}^{g+1}(k)$ by equations which are deformations of the equations of the monomial curve (see [T2], §5, proof of 5.49). Here I cheat a little by leaving out the fact that one in fact defines a formal space. Anyway, our family of (formal) curves is also defined by equations of the form:

$$\begin{aligned} u^{m^1} - u^{n^1} + \sum_{w(r)>w(m^1)} c_r^{(1)}(v)u^r &= 0 \\ u^{m^2} - u^{n^2} + \sum_{w(r)>w(m^2)} c_r^{(2)}(v)u^r &= 0 \\ \vdots & \\ u^{m^g} - u^{n^g} + \sum_{w(r)>w(m^g)} c_r^{(g)}(v)u^r &= 0 \end{aligned}$$

where the $c_r^{(j)}(v)$ are in $(v)k[[v]]$, $w(r) = \sum_0^g \gamma_j r_j$ is the weight of the monomial u^r with respect to the weight vector $w = (\gamma_0, \dots, \gamma_g)$, i.e., $w(r) = \langle w, r \rangle$. Remember that by construction $w(m^i) = w(n^i)$ for $1 \leq i \leq g$. This means that we deform each binomial equations by adding terms of weight greater than that of the binomial. It is shown in [T2] that the parametric representation and the

equational representation both describe the deformation of proposition 7.2. Up to completion with respect to the (u_0, \dots, u_g) -adic topology, the algebra $\mathcal{A}_\nu(R)$ is the quotient of $k[v][[u_0, \dots, u_g]]$ by the ideal generated by the equations written above. It is also equal to the subalgebra $k[[\xi_0(vt)v^{-\gamma_0}, \dots, \xi_g(vt)v^{-\gamma_g}]]$ of $k[v][[t]]$.

One may remark that, in the case where the $\xi_j(t)$ are polynomials, there is a close analogy with the SAGBI algebras bases for the subalgebra $k[\xi_0(t), \xi_1(t)] \subset k[t]$ (see [St]). This is developed in the text [Br] of Anna Bravo.

This equational description is the generalization of the example shown at the beginning of this section.

Now it should be more or less a computational exercise to check that a toric map $Z(\Sigma) \rightarrow \mathbf{A}^{g+1}$ which resolves the binomial variety C^Γ also resolves the “nearby fibers”, which are all isomorphic to C re-embedded in \mathbf{A}^{g+1} . There is however a difficulty (see [G-T]) which requires the use of Zariski’s main theorem.

The results of this section have been extended by P. González Pérez in [GP] to the much wider class of irreducible *quasi-ordinary* germs of hypersurface singularities, whose singularities are not isolated in general.

This shows that a toric resolution of binomial varieties can be used, by considering suitable deformations, to resolve singularities which are at first sight far from binomial.

8 Appendix:

MULTIPLICITIES, VOLUMES, AND NON DEGENERACY

8.1 Multiplicities and volumes

One of the interesting features of the Briançon-Skoda theorem is that it provides a way to pass from the integral closure of an ideal to the ideal itself, while it is much easier to check that a given element is in the integral closure of an ideal than to check that it is in the ideal. For this reason, the theorem has important applications in problems of effective commutative algebra motivated by transcendental number theory. In the same vein, this section deals, in the monomial case, with the problem of determining from numerical invariants whether two ideals have the same integral closure, which is much easier than to determine whether they are equal. The basic fact coming to light is that multiplicities in commutative algebra are like volumes in the theory of convex bodies, and indeed, for monomial ideals, they *are* volumes, up to a $d!$ factor (compare with [T3]). The same is true for degrees of invertible sheaves on algebraic varieties. Exactly as monomial ideals, and for the same reason, the degrees of equivariant invertible sheaves generated by their global sections on toric varieties *are* volumes of compact convex bodies multiplied by $d!$ (see [T1]). In this appendix proofs are essentially replaced by references.

Let R be a noetherian ring, and \mathfrak{q} an ideal of R such that the R -module R/\mathfrak{q} has finite length $\ell_R(R/\mathfrak{q}) = \ell_{R/\mathfrak{q}}(R/\mathfrak{q})$. Then the quotients $\mathfrak{q}^n/\mathfrak{q}^{n+1}$ have finite length as R/\mathfrak{q} -modules and one can define the Hilbert-Samuel series (for all this, see [B], Chap. VIII, §4)

$$H_{R,\mathfrak{q}} = \sum_{n=0}^{\infty} \ell_{R/\mathfrak{q}}(\mathfrak{q}^n/\mathfrak{q}^{n+1})T^n \in \mathbf{Z}[[T]].$$

According to *loc.cit.*, there exist an integer $d \geq 0$ and an element $P \in \mathbf{Z}[T, T^{-1}]$ such that $P(1) > 0$ and

$$H_{R,\mathfrak{q}} = (1 - T)^{-d}P.$$

From this follows the:

Proposition 8.1. (Samuel) *Given R and \mathfrak{q} as above, there exist an integer N_0 and a polynomial $Q(U)$ with rational coefficients such that for $n \geq N_0$ we have*

$$\ell_{R/\mathfrak{q}}(R/\mathfrak{q}^n) = Q(n).$$

If we assume that \mathfrak{q} is primary for some maximal ideal m of R , i.e., $\mathfrak{q} \supset m^k$ for large enough k , the degree of the polynomial Q is the dimension d of the local ring R_m , and the highest degree term of $Q(U)$ can be written $e(\mathfrak{q}, R) \frac{U^d}{d!}$. In fact (see *loc.cit.*), we have $e(\mathfrak{q}, R) = P(1) \in \mathbf{N}$.

By definition, the integer $e(\mathfrak{q}, R)$ is the *multiplicity* of the ideal \mathfrak{q} in R . If R contains a field k such that $k = R/m$, we can replace $\ell_{R/\mathfrak{q}}(R/\mathfrak{q}^n)$ by its dimension $\dim_k(R/\mathfrak{q}^n)$ as a k -vector space.

Let us take $R = k[u_1, \dots, u_d]$ and $\mathfrak{q} = (u_1^{m^1}, \dots, u_d^{m^d})R$; the ideal \mathfrak{q} is primary for the maximal ideal $m = (u_1, \dots, u_d)R$ if and only if $\dim_k R/\mathfrak{q} < \infty$. Now one sees that the images of the monomials u^m such that m is not contained in $E = \bigcup_{i=1}^d (m^i + \mathbf{R}_{\geq 0}^d)$ constitute a basis of the k -vector space R/\mathfrak{q} :

$$\dim_k R/\mathfrak{q} = \#\mathbf{Z}^d \cap (\mathbf{R}_{\geq 0}^d \setminus E).$$

For the same reason we have for all $n \geq 1$, since \mathfrak{q}^n is also monomial,

$$\dim_k R/\mathfrak{q}^n = \#\mathbf{Z}^d \cap (\mathbf{R}_{\geq 0}^d \setminus nE),$$

where nE is the set of sums of n elements of E .

From this follows, in view of the polynomial character of the first term of the equality, the:

Corollary 8.2. *Given a subset $E = \bigcup_{s=1}^d (m^s + \mathbf{R}_{\geq 0}^d)$ whose complement in $\mathbf{R}_{\geq 0}^d$ has finite volume, there exists an integer N_0 and a polynomial $Q(n)$ of degree d with rational coefficients such that for $n \geq N_0$ we have*

$$\#\mathbf{Z}^d \cap (\mathbf{R}_{\geq 0}^d \setminus nE) = Q(n).$$

Therefore, we have:

$$\lim_{n \rightarrow \infty} \frac{Q(n)}{n^d} = \lim_{n \rightarrow \infty} \frac{\#\mathbf{Z}^d \cap (\mathbf{R}_{\geq 0}^d \setminus nE)}{n^d} = \lim_{n \rightarrow \infty} \text{Covol} \frac{nE}{n} = \text{Covol} \bar{E},$$

where $\text{Covol}A$, the *covolume* of A , is the volume of the complement of A in $\mathbf{R}_{\geq 0}^d$. The last equality follows from the remark made in section 4, and the previous one from the classical fact of calculus that as $n \rightarrow \infty$, $\text{Covol} \frac{nE}{n} = \frac{\#\mathbf{Z}^d \cap (\mathbf{R}_{\geq 0}^d \setminus nE)}{n^d} + o(1)$. Since the limit as $n \rightarrow \infty$ of $\frac{Q(n)}{n^d}$ is $\frac{e(\mathbf{q}, R)}{d!}$, we have immediately the:

Corollary 8.3. *For a monomial ideal $\mathbf{q} = (u^{m_1}, \dots, u^{m_s})$ in $R = k[u_1, \dots, u_d]$ which is primary for $m = (u_1, \dots, u_d)$, with the notations above, we have the two equalities*

$$\begin{aligned} \dim_k(R/\mathbf{q}) &= \#\mathbf{Z}^d \cap (\mathbf{R}_{\geq 0}^d \setminus E) \\ e(\mathbf{q}, R) &= d! \text{Covol} \bar{E}. \end{aligned}$$

Corollary 8.4. (Monomial Rees Theorem, an avatar of [R1])

a) *For a monomial primary ideal \mathbf{q} as above, we have*

$$e(\bar{\mathbf{q}}, R) = e(\mathbf{q}, R).$$

b) *Given two such ideals $\mathbf{q}_1, \mathbf{q}_2$ such that $\mathbf{q}_1 \subseteq \mathbf{q}_2$, we have $\bar{\mathbf{q}}_1 = \bar{\mathbf{q}}_2$ if and only if $e(\mathbf{q}_1, R) = e(\mathbf{q}_2, R)$.*

These results hold (Rees' theorem, see [R1]) for ideals containing a power of the maximal ideal in a noetherian local ring R whose completion is equidimensional.

Now there is a well know theorem of Minkowski in the theory of convex bodies, concerning the volume of the Minkowski sum of compact convex sets. Recall that for K_1, K_2 in \mathbf{R}^d , the *Minkowski sum* $K_1 + K_2$ is the set of sums $\{x_1 + x_2; x_1 \in K_1, x_2 \in K_2\}$ and for $\lambda \in \mathbf{R}$, $\lambda K = \{\lambda x; x \in K\}$:

Theorem 8.5. (Minkowski) *Given s compact convex subset K_1, \dots, K_s of \mathbf{R}^d , there is a homogeneous expression for the d -dimensional volume of the positive Minkowski linear combination of the K_i , with $(\lambda_i)_{1 \leq i \leq d} \in \mathbf{R}_{\geq 0}^d$:*

$$\text{Vol}_d(\lambda_1 K_1 + \dots + \lambda_s K_s) = \sum_{\sum_1^s \alpha_i = d} \frac{d!}{\alpha_1! \dots \alpha_s!} \text{Vol}(K_1^{[\alpha_1]}, \dots, K_s^{[\alpha_s]}) \lambda_1^{\alpha_1} \dots \lambda_s^{\alpha_s},$$

where the coefficients $\text{Vol}(K_1^{[\alpha_1]}, \dots, K_s^{[\alpha_s]})$ are non negative and are called the *mixed volumes* of the convex sets K_i .

Taking $s = 2$ gives

$$\text{Vol}_d(\lambda_1 K_1 + \lambda_2 K_2) = \sum_{i=0}^d \binom{d}{i} \text{Vol}(K_1^{[i]}, K_2^{[d-i]}) \lambda_1^i \lambda_2^{d-i}.$$

The proof is obtained by approximating the convex bodies by polytopes, and using the Cauchy formula for the volume of polytopes. Exactly the same proof applies to the covolumes of *convex* subsets of $\mathbf{R}_{\geq 0}^d$ to give the corresponding theorem:

$$\text{Covol}_d(\lambda_1 \bar{E}_1 + \dots + \lambda_s \bar{E}_s) = \sum_{\sum_1^s \alpha_i = d} \frac{d!}{\alpha_1! \dots \alpha_s!} \text{Covol}(\bar{E}_1^{[\alpha_1]}, \dots, \bar{E}_s^{[\alpha_s]}) \lambda_1^{\alpha_1} \dots \lambda_s^{\alpha_s},$$

defining the *mixed covolumes* of such convex subsets.

On the other hand, there is an analogous formula in commutative algebra:

Theorem 8.6. (see [T6]): *Given ideals $\mathbf{q}_1, \dots, \mathbf{q}_s$ which are primary for a maximal ideal m in a netherian ring R such that the localization R_m is a d -dimensional local ring and the residue field R_m/mR_m is infinite, there is for $\lambda_1, \dots, \lambda_s \in \mathbf{Z}_{\geq 0}^s$ an expression*

$$e(\mathbf{q}_1^{\lambda_1} \dots \mathbf{q}_s^{\lambda_s}, R) = \sum_{\sum_1^s \alpha_i = d} \frac{d!}{\alpha_1! \dots \alpha_s!} e(\mathbf{q}_1^{[\alpha_1]}, \dots, \mathbf{q}_s^{[\alpha_s]}; R) \lambda_1^{\alpha_1} \dots \lambda_s^{\alpha_s},$$

where the coefficients $e(\mathbf{q}_1^{[\alpha_1]}, \dots, \mathbf{q}_s^{[\alpha_s]}; R)$ are non negative integers and are called the *mixed multiplicities* of the primary ideals \mathbf{q}_i . This name is justified by the fact that $e(\mathbf{q}_1^{[\alpha_1]}, \dots, \mathbf{q}_s^{[\alpha_s]}; R)$ is the multiplicity of an ideal generated by α_1 elements of $\mathbf{q}_1, \dots, \alpha_s$ elements of \mathbf{q}_s , chosen in a sufficiently general way. Taking $s = 2$ gives

$$e(\mathbf{q}_1^{\lambda_1} \mathbf{q}_2^{\lambda_2}, R) = \sum_{i=0}^d \binom{d}{i} e(\mathbf{q}_1^{[i]}, \mathbf{q}_2^{[d-i]}; R) \lambda_1^i \lambda_2^{d-i}.$$

from this and Corollary 8.3 follows immediately:

Corollary 8.7. *Let k be an infinite field. Given monomial ideals $\mathbf{q}_1, \dots, \mathbf{q}_s$ which are primary for the maximal ideal (u_1, \dots, u_d) in $R = k[u_1, \dots, u_d]$, and denoting by E_i the corresponding subsets generated by their exponents, we have for all $\alpha \in \mathbf{Z}_{\geq 0}^d$ such $\sum_1^s \alpha_i = d$ the equality*

$$e(\mathbf{q}_1^{[\alpha_1]}, \dots, \mathbf{q}_s^{[\alpha_s]}; R) = d! \text{Covol}(\bar{E}_1^{[\alpha_1]}, \dots, \bar{E}_s^{[\alpha_s]}).$$

In particular, the mixed multiplicities depend only on the integral closures of the ideals \mathbf{q}_i . Now there are well known inequalities for the mixed volumes of two compact convex bodies: the Alexandrov-Fenchel inequalities:

Theorem 8.8. (Alexandrov-Fenchel; see [Gr]) *a) Let K_1, K_2 be two compact convex bodies in \mathbf{R}^s ; set $v_i = \text{Vol}(K_1^{[i]}, K_2^{[d-i]})$. For all $2 \leq i \leq d$ the following inequalities hold:*

$$v_{i-1}^2 \geq v_i v_{i-2}.$$

b) Equality holds in all these inequalities if and only if for some $\rho \in \mathbf{R}_+$ we have $K_1 = \rho K_2$ up to translation. If all the v_i are equal, then $K_1 = K_2$ up to translation, and conversely.

Let \mathbf{B}^d denote the d -dimensional unit ball, and A any subset of \mathbf{R}^d which is tame enough for the volumes to exist.

The problem which inspired this theorem is to prove that in the isoperimetric inequality

$$\text{Vol}_{d-1}(\partial A)^d \geq d^d \text{Vol}_d(\mathbf{B}^d) \text{Vol}_d(A)^{d-1},$$

equality should hold only if A is a multiple of the unit ball, to which some "hairs" of a smaller dimension than ∂A have been added. In the case where A is convex, taking K_1 to be the unit ball and $K_2 = A$, one notices that $v_0 = \text{Vol}_d(A)$ and $v_1 = d^{-1} \text{Vol}_{d-1}(\partial A)$; the isoperimetric inequality then follows very quickly by an appropriate telescoping of the Alexandrov-Fenchel inequalities. From this telescoping follows the fact that if we have equality in the isoperimetric inequality for a convex subset A of \mathbf{R}^d , then we have equality in *all* the Alexandrov-Fenchel inequalities for A and the unit ball, so that A must be a ball. By the same type of telescoping, one proves the inequalities $v_i^d \geq v_0^{d-i} v_d^i$, which gives the:

Theorem 8.9. (Brünn-Minkowski; see [Gr]) *For convex compact subsets of \mathbf{R}^d , the following inequality holds*

$$\text{Vol}_d(K_1 + K_2)^{\frac{1}{d}} \geq \text{Vol}_d(K_1)^{\frac{1}{d}} + \text{Vol}_d(K_2)^{\frac{1}{d}},$$

with equality if and only if K_1 and K_2 are homothetic up to translation, or $\text{Vol}_d(K_1 + K_2) = 0$, or one of them is a point.

The same constructions and proof apply to covolumes, where the inequalities are reversed; they correspond to inequalities for the mixed multiplicities of monomial ideals, which are in fact true for primary ideals in formally equidimensional noetherian local rings:

Theorem 8.10. (See [T4], [R-S], [T5], [K]) *a) Let $\mathbf{q}_1, \mathbf{q}_2$ be two primary ideals in the noetherian local ring R ; set $w_i = e(\mathbf{q}_1^{[i]}, \mathbf{q}_2^{[d-i]}; R)$. For all $2 \leq i \leq d$ the following inequalities hold:*

$$w_{i-1}^2 \leq w_i w_{i-2}.$$

b) Assuming in addition that R is formally equidimensional (quasi-unmixed), equality holds in all these inequalities if and only if for some $a, b \in \mathbf{N}$ we have $\overline{\mathbf{q}_1^a} = \overline{\mathbf{q}_2^b}$. If all the w_i are equal, then $\overline{\mathbf{q}_1} = \overline{\mathbf{q}_2}$, and conversely.

So in this case again, the combinatorial inequalities appear as the avatar for monomial ideals of general inequalities of commutative algebra. One can see that if $\mathbf{q}_1 \subseteq \mathbf{q}_2$, we have $e(\mathbf{q}_1, R) = w_d \geq w_i \geq w_0 = e(\mathbf{q}_2, R)$, for $1 \leq i \leq d-1$. So this result implies Rees' Theorem, which is stated after Corollary 8.4.

In fact the same happens for the Alexandrov-Fenchel inequalities, which are the avatars for toric varieties associated to polytopes of general inequalities of Kähler geometry known as the Hodge Index Theorem. This is due to the fact that the mixed volumes of rational convex polytopes are equal, up to a $d!$ factor, to the mixed degrees of invertible sheaves (or of divisors) on certain toric

varieties associated to the collection of polytopes, exactly as in Corollary 8.7. This approach to Alexandrov-Fenchel inequalities was introduced by Khovanskii and the author; see [Gr] for an excellent exposition of this topic, and [Kh], [T1].

In all these cases, a remarkable fact is that, thanks to the positivity and convexity properties of volumes (resp., multiplicities), a *finite* number of equations on a pair (A_1, A_2) of objects in an *infinite dimensional* space (convex bodies modulo translation or integrally closed primary ideals) suffices to ensure that $A_1 = A_2$.

8.2 Newton non degenerate ideals in $k[[u_1, \dots, u_d]]$ and multiplicities

Define the support $S(I)$ of an ideal I of $k[[u_1, \dots, u_d]]$ to be the set of the exponents m appearing as one of the exponents in at least one series belonging to the ideal I . Define the Newton polyhedron $\mathcal{N}_+(I)$ of I as the boundary of the convex hull $\mathcal{P}_+(I)$ of $\bigcup_{m \in S(I)} (m + \mathbf{R}_{\geq 0}^d)$.

According to [B-F-S], a primary ideal \mathbf{q} is said to be *non degenerate* if it admits a system of generators q_1, \dots, q_t such that their restrictions to each compact face of $\mathcal{N}_+(I)$ have no common zero in the torus $(k^*)^d$. The following is part of what is proved in [B-F-S], §3:

Theorem 8.11. ([B-F-S]) *For a primary ideal \mathbf{q} of $R = k[[u_1, \dots, u_d]]$, the following conditions are equivalent:*

- a) *The ideal \mathbf{q} is non degenerate in the coordinates u_1, \dots, u_d ,*
- b) *The equality $e(\mathbf{q}, R) = d! \text{Covol} \mathcal{P}_+(I)$ holds,*
- c) *The integral closure $\bar{\mathbf{q}}$ of \mathbf{q} is generated by monomials in u_1, \dots, u_d .*

It follows from this that monomial ideals are non degenerate, and that products of non degenerate primary ideals are non degenerate ([B-F-S], Corollary 3.14). Moreover, all the numerical facts mentioned above for monomial ideals with respect to their Newton polyhedron are valid for non degenerate ideals (*loc.cit.*). Non degenerate ideals behave as *reductions* of monomial ideals, which in fact they are. Here we can think of a reduction (in the sense of Northcott-Rees; see [N-R], [R3]) of an ideal $\mathcal{M} \subset k[[u_1, \dots, u_d]]$ as an ideal generated by d sufficiently general combinations of generators of \mathcal{M} . More precisely, it is an ideal \mathcal{M}' contained in \mathcal{M} and having the same integral closure.

There is a close connection between this non degeneracy for ideals and the results of section 5; if the ideal $\mathbf{q} = (q_1, \dots, q_s)k[[u_1, \dots, u_d]]$ is non degenerate, then a general linear combination $q = \sum_{i=1}^s \lambda_i q_i$ is non degenerate with respect to its Newton polyhedron.

There are many other interesting consequences of the relationship between monomial ideals and combinatorics; I refer the reader to [St].

All the results of this appendix remain valid if $k[[u_1, \dots, u_d]]$ and its completion $k[[u_1, \dots, u_d]]$ are replaced respectively by $k[\tilde{\sigma} \cap \mathbf{Z}^d]$ and its completion, for a strictly convex cone $\sigma \subset \mathbf{R}_{\geq 0}^d$.

There are also generalizations of mixed multiplicities to collections of not necessarily primary ideals (see [R2]) and to the case where one of the ideals is replaced by a submodule of finite colength of a free R -module of finite type (see [K-T]).

It would be interesting to determine how the results of this appendix extend to monomial submodules of a free $k[u_1, \dots, u_d]$ -module.

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