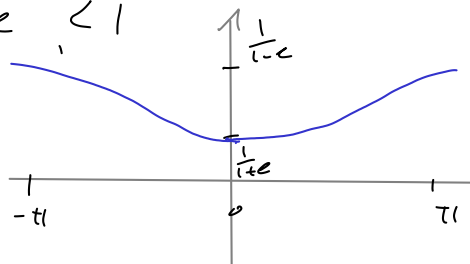


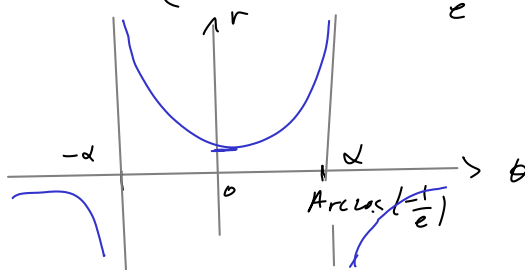
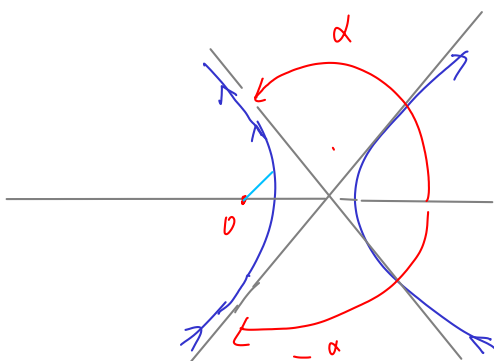
Devoir pour le 23 mars : à rendre jusqu'au 30 mars.

$$r = \frac{h}{1 + e \cos \theta}$$

$$0 < e < 1$$



$$1 < e : 1 + e \cos \theta = 0 \quad (\Rightarrow) \quad \cos \theta = -\frac{1}{e} \in ]-1, 0[.$$



### Equations de Hamilton.

Si  $\gamma : \mathbb{R} \rightarrow \mathbb{R}^3$  décrit le mouvement d'un point dans l'espace physique.

ou  $\Omega : \text{ouvert} \subset \mathbb{R}^3$

Sur  $\Omega \times \mathbb{R}^3$  on définit

$(x, p)$   
 $\uparrow \quad \uparrow$   
 position | moments cinétiques  
 (ou impulsion)

$$H : \Omega \times \mathbb{R}^3 \rightarrow \mathbb{R} \quad (\text{Hamiltonien})$$

$$(x, p) \mapsto H(x, p)$$

Exemple :

$$H(x, p) = V(x) + \frac{\|p\|^2}{2m}$$

"énergie potentielle"

Rappel :  $p = m v \Rightarrow \|p\|^2 = m^2 \|v\|^2$

$$\Rightarrow \frac{\|p\|^2}{2m} = \frac{1}{2} m \|v\|^2 \quad (\text{énergie cinétique})$$

$$(\gamma : I \rightarrow \Omega) \rightarrow h(t) = \begin{pmatrix} \gamma(t) \\ m \dot{\gamma}(t) \end{pmatrix} \in \Omega \times \mathbb{R}^3 \subset \mathbb{R}^3 \times \mathbb{R}^3 \simeq \mathbb{R}^6$$

$$= \begin{pmatrix} \gamma(t) \\ \pi(t) \end{pmatrix} \quad \text{car } \pi(t) = m \dot{\gamma}(t)$$

Hamilton

$$\begin{cases} \frac{d\gamma^i}{dt} = \frac{\partial H}{\partial p_i}(\gamma, \pi) = \frac{\partial H}{\partial p_i} \circ h = \frac{\pi_i}{m} \\ \frac{d\pi_i}{dt} = -\frac{\partial H}{\partial x^i}(\gamma, \pi) = -\frac{\partial H}{\partial x^i} \circ h = -\frac{\partial V}{\partial x^i}(\gamma) \end{cases}$$

$$\left. \begin{aligned} \frac{\partial H}{\partial p_i}(\gamma, \pi) &= \frac{\partial}{\partial p_i} \left[ V(x) + \frac{\|p\|^2}{2m} \right] = \frac{1}{2m} 2p_i = \frac{p_i}{m} \Rightarrow \frac{\partial H}{\partial p_i} \circ h = \frac{\partial H}{\partial p_i}(\gamma, \pi) = \frac{\pi_i}{m} \\ \frac{\partial H}{\partial x^i}(\gamma, \pi) &= \frac{\partial V}{\partial x^i}(\gamma) \Rightarrow -\frac{\partial H}{\partial x^i} \circ h = -\frac{\partial H}{\partial x^i}(\gamma, \pi) = -\frac{\partial V}{\partial x^i}(\gamma) \end{aligned} \right\}$$

$V(x) = -\frac{G m_1 m_2}{\|x\|}$  par exemple

Hamilton  $\Leftrightarrow$

$$\begin{cases} \frac{d\gamma^i}{dt} = \frac{\pi_i}{m} \Leftrightarrow \pi_i = m \frac{d\gamma^i}{dt} \\ \boxed{m \frac{d^2\gamma^i}{dt^2}} = \frac{d}{dt} \left( m \frac{d\gamma^i}{dt} \right) = \frac{d\pi_i}{dt} = \boxed{-\frac{\partial V}{\partial x^i}(\gamma)} \end{cases} \quad (\text{force d\u00e9rivant d'un potentiel})$$

Marche toutes les fois que  $F(x) \text{ (force)} = -\underbrace{\nabla V(x)}_{\text{gradient}}$  (gradient de  $V: \mathbb{R}^3 \rightarrow \mathbb{R}$ )

Cas de deux corps massifs en interaction (lié au devoir)

Deux corps A et B, masses  $m_A$  et  $m_B$ , positions  $\gamma_A: \mathbb{R} \rightarrow \mathbb{R}^3$   
 $\gamma_B: \mathbb{R} \rightarrow \mathbb{R}^3$

Principe d'action & réaction:  $F_{A/B} = -F_{B/A}$

$$\Rightarrow \frac{d}{dt} (m_A \dot{\gamma}_A + m_B \dot{\gamma}_B) = 0$$

Cas

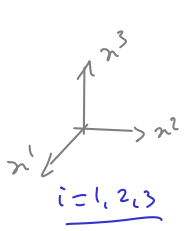
$$\begin{cases} m_A \ddot{\gamma}_A = -\frac{G m_A m_B}{\|\gamma_A - \gamma_B\|} (\gamma_A - \gamma_B) \\ m_B \ddot{\gamma}_B = -\frac{G m_A m_B}{\|\gamma_A - \gamma_B\|} (\gamma_B - \gamma_A) \end{cases}$$

$$m: \mathbb{R} \rightarrow \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3$$

$\hookrightarrow$   $\begin{matrix} \text{(position A)} & \text{(position B)} & \text{(impulsion A)} & \text{(impulsion B)} \\ (\gamma_A(t)) & (\gamma_B(t)) & (\pi_A(t)) & (\pi_B(t)) \end{matrix}$

$$H : \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \longrightarrow \mathbb{R}$$

$$(x_A, x_B, p_A, p_B) \longmapsto H(x_A, x_B, p_A, p_B)$$



$$H(x_A, x_B, p_A, p_B) = \underbrace{-\frac{G m_A m_B}{\|x_A - x_B\|}}_{\text{énergie (potentielle) d'interaction gravitationnelle}} + \underbrace{\frac{\|p_A\|^2}{2m_A} + \frac{\|p_B\|^2}{2m_B}}_{\text{somme des énergies cinétiques}} \quad (\text{énergie totale du système})$$

$$\frac{dx_A^i}{dt} = \frac{\partial H}{\partial p_{A i}}(x, \pi) ; \quad \frac{dx_B^i}{dt} = \frac{\partial H}{\partial p_{B i}}(x, \pi) \quad \longleftarrow \frac{d}{dt} (\text{positions des particules})$$

$$\frac{d\pi_{A i}}{dt} = -\frac{\partial H}{\partial x_A^i}(x, \pi) ; \quad \frac{d\pi_{B i}}{dt} = -\frac{\partial H}{\partial x_B^i}(x, \pi) \quad \longleftarrow \frac{d}{dt} (\text{impulsions})$$

$$\frac{\partial H}{\partial p_{A i}}(x, p) = \frac{p_{A i}}{m_A} ; \quad \frac{\partial H}{\partial p_{B i}}(x, p) = \frac{p_{B i}}{m_B}$$

$$\frac{\partial H}{\partial x_A^i}(x, p) = \frac{\partial}{\partial x_A^i} \left( -\frac{G m_A m_B}{\|x_A - x_B\|} \right) = \left( -G m_A m_B \right) \frac{-1}{2 (\|x_A - x_B\|^2)^{3/2}} x_A^i$$

$$\left( \begin{array}{l} (x_A, x_B) \longmapsto \sum_{i=1}^3 (x_A^i - x_B^i)^2 = \|x_A - x_B\|^2 \xrightarrow{F} -\frac{G m_A m_B}{\|x_A - x_B\|^3} \\ \mathbb{R}^6 \setminus \{(x, x)\} \xrightarrow{G} \mathbb{R} \setminus \{0\} \xrightarrow{F} \mathbb{R} \end{array} \right)$$

$$\frac{\partial (F \circ G)}{\partial x_A^i}(x_A, x_B) = F'_3 \circ G(x_A, x_B) \quad \frac{\partial G}{\partial x_A^i}(x_A, x_B)$$

$$= \frac{G m_A m_B}{\|x_A - x_B\|^3} x_A^i$$

De même  $\frac{\partial H}{\partial x_B^i} = \frac{G m_A m_B}{\|x_A - x_B\|^3} x_B^i$

→ Hamilton

$$\left\{ \begin{array}{l} \dot{x}_A^i = \frac{\pi_{A i}}{m_A} \quad \dot{x}_B^i = \frac{\pi_{B i}}{m_B} \quad (\Rightarrow) \left( \begin{array}{l} \pi_{A i} = m_A \dot{x}_A^i \\ \pi_{B i} = m_B \dot{x}_B^i \end{array} \right. \\ \dot{\pi}_{A i} = -\frac{G m_A m_B}{\|x_A - x_B\|^3} x_A^i \quad \dot{\pi}_{B i} = -\frac{G m_A m_B}{\|x_A - x_B\|^3} x_B^i \end{array} \right.$$

$$\Rightarrow m_A \ddot{x}_A^i = -\frac{G m_A m_B}{\|x_A - x_B\|^3} x_A^i \quad \& \quad m_B \ddot{x}_B^i = -\frac{G m_A m_B}{\|x_A - x_B\|^3} x_B^i$$

Conservation de l'énergie:

$$\mathbb{R} \xrightarrow{(\delta, \pi)} \mathbb{R}^6 \xrightarrow{H} \mathbb{R}$$

$$H(x, p) = V(x) + \frac{\|p\|^2}{2m}$$

$\pi = m\dot{x}$

$H \circ (\delta, \pi) = E$  : fonction qui donne <sup>l'énergie</sup> de la particule à chaque instant.

$$(H \circ (\delta, \pi)) \circ \Gamma = V(r) + \frac{\|\dot{r}\|^2}{2m} = V(r) + \frac{m \|\dot{r}\|^2}{2} \quad : \text{énergie à l'instant } t.$$

Retrouvons cela:

$$\frac{dE}{dt} = \frac{dH \circ (\delta, \pi)}{dt} = \sum_{i=1}^3 \frac{\partial H}{\partial x^i} (\delta, \pi) \frac{d\delta^i}{dt} + \sum_{i=1}^3 \frac{\partial H}{\partial p_i} (\delta, \pi) \frac{d\pi_i}{dt}$$

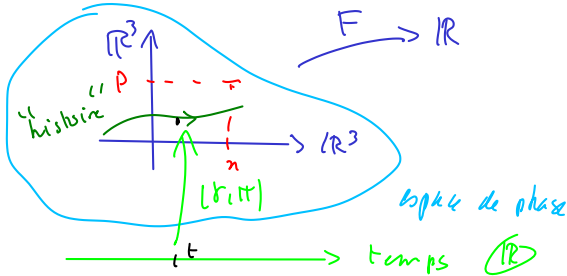
$$\begin{aligned} \mathbb{R}^u \xrightarrow{\mathbb{R}^p} \mathbb{F} \rightarrow \mathbb{R} \\ \frac{d(F \circ u)}{dt} = \sum_{\alpha=1}^p \left( \frac{\partial F}{\partial x^\alpha} \circ u \right) \frac{dx^\alpha}{dt} \\ = \left\langle \left( \frac{\partial F}{\partial x} \right) \circ u, \frac{du}{dt} \right\rangle \end{aligned}$$

si  $(\delta, \pi)$  est solution des équations de Hamilton

$$= \sum_{i=1}^3 \frac{\partial H}{\partial x^i} (\delta, \pi) \frac{\partial H}{\partial p_i} (\delta, \pi) + \sum_{i=1}^3 \frac{\partial H}{\partial p_i} (\delta, \pi) \left( -\frac{\partial H}{\partial x^i} (\delta, \pi) \right)$$

$= 0 \rightarrow$  conservation de  $E(t)$  si  $(\delta, \pi)$  est solution de Hamilton.

Que se passe-t-il pour n'importe quelle  $F: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$  ?



Calculer  $\frac{d(F \circ (\delta, \pi))}{dt}$

sachant que  $(\delta, \pi)$  est solution de Hamilton

$$H \quad \begin{cases} \frac{d\delta^i}{dt} = \frac{\partial H}{\partial p_i} (\delta, \pi) \\ \frac{d\pi_i}{dt} = -\frac{\partial H}{\partial x^i} (\delta, \pi) \end{cases}$$

$$\frac{d(F \circ u)}{dt} = \sum_{\alpha=1}^p \left( \frac{\partial F}{\partial x^\alpha} \circ u \right) \frac{dx^\alpha}{dt}$$

$$\begin{aligned} \mathbb{R}^u \xrightarrow{\mathbb{R}^p} \mathbb{F} \rightarrow \mathbb{R} \\ \frac{d}{dt} [F \circ (\delta, \pi)] &= \sum_{i=1}^3 \frac{\partial F}{\partial x^i} (\delta, \pi) \frac{d\delta^i}{dt} + \sum_{i=1}^3 \frac{\partial F}{\partial p_i} (\delta, \pi) \frac{d\pi_i}{dt} \\ &= \sum_{i=1}^3 \frac{\partial F}{\partial x^i} (\delta, \pi) \frac{\partial H}{\partial p_i} (\delta, \pi) + \frac{\partial F}{\partial p_i} (\delta, \pi) \left( -\frac{\partial H}{\partial x^i} (\delta, \pi) \right) \\ &= \{H, F\} (\delta, \pi) \end{aligned}$$

$$\text{on } \left\{ H, F \right\} (x, p) := \sum_{i=1}^3 \frac{\partial H}{\partial p_i} (x, p) \frac{\partial F}{\partial x_i} (x, p) - \frac{\partial H}{\partial x_i} (x, p) \frac{\partial F}{\partial p_i} (x, p)$$

Crochet de Poisson de H et F.

Théorème Si  $(\delta, \pi)$  est solution de  $\frac{dx^i}{dt} = \frac{\partial H}{\partial p_i} \circ (\delta, \pi)$  &  $\frac{dp_i}{dt} = -\frac{\partial H}{\partial x_i} \circ (\delta, \pi)$

$$\text{Alors } \frac{d(F \circ (\delta, \pi))}{dt} = \{H, F\} \circ (\delta, \pi)$$

ça généralise à N particules :  $H, F : (\mathbb{R}^3)^N \times (\mathbb{R}^3)^N \rightarrow \mathbb{R}$   
(positions) (impulsions)

Exemple 2 particules A et B dans  $\mathbb{R}^3$

$$H(x_A, x_B, p_A, p_B) = \frac{\|p_A\|^2}{2m_A} + \frac{\|p_B\|^2}{2m_B} + \frac{G m_A m_B}{\|x_A - x_B\|}$$

$$F = m_A x_A^1 + m_B x_B^1 \quad (\text{première composante de } m_A x_A + m_B x_B)$$

$$\begin{aligned} \{H, F\} &= \sum_{i=1}^3 \frac{\partial H}{\partial p_{A_i}} \frac{\partial F}{\partial x_{A_i}} + \frac{\partial H}{\partial p_{B_i}} \frac{\partial F}{\partial x_{B_i}} - \frac{\partial H}{\partial x_{A_i}} \frac{\partial F}{\partial p_{A_i}} - \frac{\partial H}{\partial x_{B_i}} \frac{\partial F}{\partial p_{B_i}} \\ &= \frac{\partial H}{\partial p_{A1}} m_A + \frac{\partial H}{\partial p_{B1}} m_B - \frac{\partial H}{\partial x_{A1}} \underbrace{\frac{\partial F}{\partial p_{A1}}}_0 - \frac{\partial H}{\partial x_{B1}} \underbrace{\frac{\partial F}{\partial p_{B1}}}_0 \end{aligned}$$

$$= \frac{p_{A1}}{m_A} m_A + \frac{p_{B1}}{m_B} m_B = p_{A1} + p_{B1} =: P_1 \quad (\text{quantité de mouvement totale})$$

$$G = p_{A1} + p_{B1} \quad \Rightarrow \quad \frac{\partial G}{\partial x_{A_i}} = \frac{\partial G}{\partial x_{B_i}} = 0 \quad \text{et} \quad \frac{\partial G}{\partial p_{A1}} = 1, \quad \frac{\partial G}{\partial p_{B1}} = 1$$

$$\begin{aligned} \{H, G\} &= \left( \sum_{i=1}^3 \frac{\partial H}{\partial p_{A_i}} \times 0 + \frac{\partial H}{\partial p_{B_i}} \times 0 \right) - \frac{\partial H}{\partial x_{A1}} \times 1 - \frac{\partial H}{\partial x_{B1}} \times 1 \\ &= -\frac{\partial H}{\partial x_{A1}} - \frac{\partial H}{\partial x_{B1}} \end{aligned}$$

$$\text{Or } H = \frac{\|p_A\|^2}{2m_A} + \frac{\|p_B\|^2}{2m_B} - \frac{G m_A m_B}{\|x_A - x_B\|}$$

$$\frac{\partial}{\partial x_{A1}} (\|x_A - x_B\|^2) = 2(x_{A1} - x_{B1})$$

$$\frac{\partial}{\partial x_{B1}} (\|x_A - x_B\|^2) = 2(x_{B1} - x_{A1})$$

$$\|x_A - x_B\|^2 = \sum_{i=1}^3 (x_{A_i} - x_{B_i})^2$$

$$\Rightarrow \forall f : \mathbb{R}_+ \rightarrow \mathbb{R} \quad \frac{\partial f(\|x_A - x_B\|^2)}{\partial x_{A1}} + \frac{\partial f(\|x_A - x_B\|^2)}{\partial x_{B1}} = 0$$

Donc  $\{H, p_A^1 + p_B^1\} = 0.$

$G(x, p) = p_A^1 + p_B^1$

Conséquence  $\frac{d(\pi_A^1 + \pi_B^1)}{dt} = \frac{dG_0(t, \pi)}{dt} = \underbrace{\{H, G\}}_{\text{toujours nul}}(t, \pi) = 0$

Conclusion :  $\pi_A^i + \pi_B^i$  est conservée,  $\forall i = 1, 2, 3.$   
 (quantité de mouvement totale)

Lien avec principe d'incertitude ("indetermination") de Heisenberg.

|| On ne peut pas déterminer position et impulsion simultanément avec une précision arbitraire.

$p_1 : \mathbb{R}^6 \rightarrow \mathbb{R}, \quad x^i : \mathbb{R}^6 \rightarrow \mathbb{R}$   
 "fonction "position"  
 (observable)

$$\{p_1, x^1\} = \sum_{i=1}^3 \frac{\partial p_1}{\partial x^i} \frac{\partial x^1}{\partial x^i} - \frac{\partial p_1}{\partial x^1} \frac{\partial x^1}{\partial x^i}$$

$$= 1 \cdot 1 + 0 \cdot 0 + 0 \cdot 0 - 0 \cdot 0 = 1.$$

$\{p_1, x^1\} = 1$