

MORSE THEORY AND GLOBAL COEXISTENCE OF
SINGULARITIES ON WAVE FRONTS

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ABSTRACT

We produce examples of Legendrian isotopy classes in $ST^*\mathbb{R}^n$ (the space of cooriented contact elements of \mathbb{R}^n , endowed with its standard contact structure) such that any element of those classes has a singular (non-immersed) wave front, that is, the projection to the base of the fibration $ST^*\mathbb{R}^n \rightarrow \mathbb{R}^n$, when restricted to such a Legendrian embedding, has local singularities. Furthermore, our examples are such that the underlying Legendrian homotopy classes contain some Legendrian embeddings whose wave fronts are immersed. These examples are motivated by a question of Arnold about the removability of singularities of wave fronts by means of Legendrian isotopy. The two key points, which are of independent interest, are as follows.

(1) A duality argument which allows the question to be translated into a problem about Legendrian submanifolds of the one-jets space of the sphere, and hence to use the technology of *generating families*.

(2) Several independent constructions of families of functions on compact manifolds such that the ‘critical sets’ of these families are connected. For example, we prove that given two compact, connected manifolds M and N of positive dimension, there exists

$$f : N \times M \rightarrow \mathbb{R}, (x, y) \rightarrow f(x, y), \quad x \in N, y \in M$$

such that the equation $(\partial f / \partial y)(x, y) = 0$ is regular and defines a smooth and *connected* submanifold of $M \times N$.

1. Introduction

The results presented in this paper were motivated by a question of Arnold [1, 2] about the removability of singularities of wave fronts by means of Legendrian isotopy. This question was solved (simultaneously and independently) by Entov [12] and the present authors [16]. In the present paper, we generalize and make explicit some constructions which were only sketched[†] in [16]. The methods of [12] are close to ours (generating families, Morse theory) but nevertheless different. We use a version of projective duality and exploit the relationship between the singularities of a wave front and those of its dual (Section 2 below). We present four natural constructions of families of functions with a connected ‘critical set’ (Propositions A, B, C and D below). Manifolds with this property are a key ingredient to produce examples that answer the question of Arnold.

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[†]The present paper is an evolution of the preprint [17], which already contained the full proofs of the results sketched in [16].

01 A cooriented contact element at some point q of a manifold M is a cooriented
 02 hyperplane in T_qM . The space ST^*M of all cooriented contact elements of M is the
 03 fiberwise spherization of the cotangent bundle T^*M . It has a natural contact struc-
 04 ture (i.e. an everywhere maximally non-integrable field of tangent hyperplanes), Q1
 05 defined by the following construction. Denote by $\pi : ST^*M \rightarrow M$ the natural
 06 projection. A vector X , tangent to ST^*M at some contact element κ , belongs to
 07 the contact distribution if $\pi_*X \in TM$ lies in κ . A submanifold which is everywhere
 08 tangent to some contact structure is called *isotropic*. Its dimension cannot exceed
 09 $n - 1$, where $2n - 1$ is the dimension of the ambient contact manifold. An isotropic
 10 submanifold of maximal dimension is called *Legendrian*. For instance, the fibers of
 11 π are Legendrian spheres. The projection $\pi(L)$ of a Legendrian $L \subset ST^*M$ is called
 12 the wave front (or simply *the front*) of L . In general, $\pi|_L$ is not an immersion. When
 13 M is a surface, a generic front is a curve on M whose singularities are semi-cubic
 14 cusps and transverse self-intersections.

15
 16 DEFINITION. Two compact Legendrian submanifolds are said to be *Legendrian*
 17 *isotopic* (respectively *Legendrian homotopic*) if they can be joined by a smooth
 18 one-parameter family of Legendrian embeddings (respectively immersions).

19
 20 Let M be a manifold whose universal cover is \mathbb{R}^n .

21
 22 MAIN THEOREM. *There exists an embedded Legendrian submanifold $L \subset$*
 23 *ST^*M such that:*

- 24 • *any L' Legendrian isotopic to L has a non-immersed front ($\pi|_{L'}$ is not an*
 25 *immersion);*
- 26 • *there exists L'' , Legendrian homotopic to L , whose front is an immersed (and*
 27 *even embedded) hypersurface in M .*

28
 29 In the case when M is the plane \mathbb{R}^2 , this theorem answers a question formulated
 30 by Arnold in [1] and in [2, Section 11]: Is it possible to deform a singular planar
 31 wave front into a smooth immersed curve by means of a Legendrian isotopy of the
 32 underlying Legendrian knot? This theorem implies that the answer is negative, even
 33 when some obvious obstructions such as the Maslov class are trivial. Note that it
 34 is enough to prove the theorem in the case $M = \mathbb{R}^n$.

35 A crucial step in the proof (see Section 3.4) can be interpreted as a particular
 36 case of the second author's 'Sturm-like' theory of the Maslov class (see [20]), but
 37 our proof is exposed here in an independent, self-contained way.

38 In the case when $n = 2$, this theorem contrasts with the following result, proved
 39 in [14]. Consider a front on a surface for which there is no homotopical obstruction
 40 to cusps cancellation. Then one can achieve cusps cancellation by a Legendrian
 41 isotopy *after stabilization*: assume that one can remove the singularities of the
 42 front of some Legendrian knot L by a deformation through Legendrian immersions.
 43 Then, after an appropriate 'connected sum', defined in [14], with sufficiently many
 44 copies of the same standard Legendrian knot, one can cancel the singularities of
 45 the front of L by a deformation of L through Legendrian embeddings.

46 Note that [14] also contains a theorem about the necessity of cusps for fronts,
 47 but in the context of the contact manifold $PT^*\mathbb{R}^2$ (the projectivization of the
 48 cotangent bundle of the plane). It may look similar to the Main Theorem above,
 49 but the difficulties are, in fact, of a very different nature.

50

01 This paper is organized as follows. In Section 2, we recall a classical construction,
 02 which will be used later to translate our problems in terms of Morse theory.
 03 The Main Theorem is proved in Section 3, modulo some constructions which are
 04 presented in Section 4.

05 See [4] (in particular, Chapter 4, Section 1 and Chapter 5, Section 1) for all of
 06 the basic results of contact topology used throughout this paper without proof.

07
 08
 09

2. A preliminary construction

10 The following construction is a contact-geometric version of the theory of support
 11 functions of convex bodies in the Euclidean space.

12
 13 2.1. One-jets spaces

14 Given some compact manifold N , denote by $J^1(N, \mathbb{R}) = T^*N \times \mathbb{R}$ the space of
 15 one-jets of functions on the N . It has a natural contact structure, induced by the
 16 contact form $du - pdq$, where $p dq$ stands for the canonical one-form (the Liouville
 17 form) of T^*N and u denotes a coordinate along the \mathbb{R} factor.

18 Denote by σ the projection $J^1(N, \mathbb{R}) \rightarrow J^0(N, \mathbb{R}) = N \times \mathbb{R}$. This projection has
 19 Legendrian fibers with respect to the above contact structure. We describe below a
 20 classical contactomorphism between $ST^*\mathbb{R}^n$ and $J^1(S^{n-1}, \mathbb{R})$, endowed with their
 21 natural contact structures.

22
 23

24 2.2. Choose an origin in \mathbb{R}^n . Identify $ST^*\mathbb{R}^n$ with $\mathbb{R}^n \times S^{n-1}$, where S^{n-1} is the
 25 unit sphere in $\mathbb{R}^n = T_0^*\mathbb{R}^n$. Denote by (Q, θ) a point in $\mathbb{R}^n \times S^{n-1}$, with $Q \in \mathbb{R}^n$
 26 and θ a unit vector, and by $\langle \cdot, \cdot \rangle$ the standard scalar product of \mathbb{R}^n . The one-
 27 form $\langle \theta, dQ \rangle$ induces the contact structure on $ST^*\mathbb{R}^n$. Using the standard metric
 28 of the Euclidean sphere to identify its tangent and cotangent bundles, a point in
 29 $J^1(S^{n-1}, \mathbb{R})$ can be identified with (θ, p, u) , where p is a (co)vector (co)tangent to
 30 the sphere at θ , and u is a real number. In these coordinates, the standard contact
 31 form of $J^1(S^{n-1}, \mathbb{R})$ is $du - p d\theta$.

32
 33

PROPOSITION. Denote by H the mapping defined by the following formula:

34
 35
 36

$$\begin{aligned} ST^*\mathbb{R}^n &\rightarrow J^1(S^{n-1}, \mathbb{R}) \\ (Q, \theta) &\rightarrow (\theta, p = Q_{\theta^\perp}, u = \langle \theta, Q \rangle) \end{aligned}$$

37 where Q_{θ^\perp} denotes the projection of the vector Q to the hyperplane tangent to the
 38 sphere at θ . Then, H conjugates the two standard contact forms:

39
 40

$$H^*(du - p d\theta) = \langle \theta, dQ \rangle.$$

41
 42

Proof. It is a direct computation. □

43
 44

Using this notation, this mapping H has an inverse given by the formula

45
 46
 47

$$\begin{aligned} J^1(S^{n-1}, \mathbb{R}) &\rightarrow ST^*\mathbb{R}^n \\ (\theta, p, u) &\rightarrow (Q = u \cdot \theta + p, \theta). \end{aligned}$$

48 From now on, we identify these two contact manifolds by means of this contacto-
 49 morphism. Our contact manifold is now equipped with two Legendrian fibrations, π

50

01 and σ . At any point of the contact manifold, the tangent spaces to the two fibers are
 02 transversal in the contact hyperplane, and hence generate the contact hyperplane.

04 2.3. Terminology

05 Given a Legendrian submanifold $L \subset ST^*\mathbb{R}^n \equiv J^1(S^{n-1}, \mathbb{R})$, we call $\sigma(L)$ its
 06 0-jet front and $\pi(L)$ its Euclidean front. These two fronts are said to be dual to
 07 each other.

10 3. The Maslov class

11 Consider a Legendrian submanifold $L \subset ST^*\mathbb{R}^n \equiv J^1(S^{n-1}, \mathbb{R})$. Denote by C_σ
 12 (respectively C_π) the set of points in the neighborhood of which $\sigma|_L$ (respectively
 13 $\pi|_L$) is not an immersion. We want to show that there exists some L with the
 14 following properties: (i) it is impossible to deform L through Legendrian embeddings
 15 such that the subset C_π of this deformed submanifold becomes empty; (ii) it is
 16 possible to achieve this by a deformation through Legendrian immersions.

17 For L in general position with respect to the projections π and σ , C_π and C_σ are
 18 codimension-one, possibly singular subsets of L (see [4, Chapter 6, Section 1]). We
 19 will call the Legendrian submanifolds having this property *generic*.

20 The smooth part of C_σ has a natural coorientation which we recall below in
 21 Section 3.3. Intersection of C_σ with loops in L induces a well-defined class in
 22 $H^1(L, \mathbb{Z})$, the Maslov class. This cohomology class is invariant under deformations
 23 through Legendrian immersions.

25 3.1. The strategy of the proof of the Main Theorem

26 Given a generic Legendrian submanifold $L \subset ST^*\mathbb{R}^n$, we will define a function
 27 ind_{C_σ} defined on paths $\gamma : [0, 1] \rightarrow L$ with endpoints outside of C_σ . We will show
 28 that this function has the property that, for any path $\gamma : [0, 1] \rightarrow L \setminus C_\pi$ with
 29 endpoints outside C_σ , $|\text{ind}_{C_\sigma}(\gamma)|$ is not larger than $n - 1$ (see the Proposition in
 30 Section 3.4).

31 A second step in the proof is to show that there exists some Legendrian isotopy
 32 classes in $J^1(S^{n-1}, \mathbb{R})$ such that for any generic L belonging to them, there exists a
 33 path $\gamma : [0, 1] \rightarrow L$ with endpoints outside of C_σ , such that $\text{ind}_{C_\sigma}(\gamma)$ is not smaller
 34 than n . Several independent constructions of such Legendrian isotopy classes are
 35 given in Section 4.

36 Together, these two inequalities imply that C_π is non-empty and, hence, that
 37 there exists Legendrian isotopy classes with generic representatives that all have
 38 a non-immersed Euclidean front. However, immersions are stable, so non-generic
 39 representatives also have a non-immersed Euclidean front.

40 **REMARK.** Loosely speaking, the first step described above has the following
 41 cohomological interpretation. Using intersection duality, 1-cochains can be associ-
 42 ated to the singular sets C_π and C_σ . These two 1-cochains happen to be cocycles.
 43 Furthermore, they both induce the same class in $H^1(L, \mathbb{Z})$. Their difference is the
 44 boundary of an explicit 0-cochain whose variation is less than n . However, the formal
 45 definition of these cochains is cumbersome, and can be avoided for our purposes,
 46 as shown below.

3.2. Generating families

Let N and V be manifolds without boundary, not necessarily closed. A *generating family* is some function $F : N \times V \rightarrow \mathbb{R}$ to which we associate the subset $L_F \subset J^1(N, \mathbb{R})$ defined by the following parameterization:

$$L_F = \left\{ (u, q, p) \mid \exists v \in V \text{ such that } u = F(q, v), p = \frac{\partial F}{\partial q}(q, v), \frac{\partial F}{\partial v}(q, v) = 0 \right\}$$

where (q, p) abusively denotes an element of T^*N . If $\partial F/\partial v$ is transversal over 0, then L_F is an immersed (generically embedded) Legendrian submanifold. Locally, any Legendrian submanifold $L \subset J^1(N, \mathbb{R})$ is induced by such a generating family: for any point $P \in L$, there exists an *auxiliary manifold* V and a function $F : N \times V \rightarrow \mathbb{R}$ such that L coincides with L_F near P .

3.3. The natural coorientation of C_σ

This is given by the following construction. Consider a path $\gamma : [0, 1] \rightarrow L$ with endpoints outside of C_σ , and which is completely contained in some open ball where L is identical to some L_F . The piece of C_σ which is contained in this ball corresponds to the (θ, v) such that the matrix $(\partial^2 F/\partial v^2)(\theta, v)$ is singular. The intersection between C_σ and γ is defined by the formula

$$\text{ind}_{C_\sigma}(\gamma) = \text{ind}_v(F, \gamma(1)) - \text{ind}_v(F, \gamma(0)),$$

where $\text{ind}_v(F, x)$ is the index of the quadratic form $(\partial^2 F/\partial v^2)(\theta, v)$ at the point (θ, v) which parameterizes $x \in L$. This difference is independent of the choice of the generating family F (see [20] and [4, Chapter 6, Section 1]).

REMARK. If the Legendrian submanifold L is globally defined by a single generating family[†], the formula above makes sense not only for the ‘small’ paths as above, but also for any path γ with endpoints outside of C_σ .

Assume now that L is generic, so that C_σ is of codimension one. A path $\gamma : [0, 1] \rightarrow L$ with endpoints outside of C_σ can be homotoped relatively to its endpoints to a path having only a finite number of intersections with C_σ . The integer $\text{ind}_{C_\sigma}(\gamma)$ is defined to be the sum of the local contributions of each of the intersection points, computed as above. In this way $\text{ind}_{C_\sigma}(\gamma)$ is (well) defined for all paths $\gamma : [0, 1] \rightarrow L$ with endpoints outside of C_σ , provided that L is generic.

3.4. Estimation from above of $|\text{ind}_{C_\sigma}(\gamma)|$ for paths γ in $L \setminus C_\pi$

Denote by W a connected component of the open set $L \setminus C_\pi$.

PROPOSITION. *Assume that a path γ takes its values in W . Then $|\text{ind}_{C_\sigma}(\gamma)| \leq n - 1$.*

Proof. Denote by $F : S^{n-1} \times W \rightarrow \mathbb{R}$ the smooth function defined by $F(\theta, w) = \langle \pi(w), \theta \rangle$. Denote by \mathcal{L} the Legendrian submanifold of $J^1(S^{n-1}, \mathbb{R}) \cong ST^*\mathbb{R}^n$ induced by F as in Section 3.2.

[†]This will be the case of all the Legendrian submanifolds considered in the following.

01 CLAIM. We claim that W is a connected component of \mathcal{L} .

02
03 The proposition follows from this claim. The ‘auxiliary manifold’ of the generating
04 family F is the open manifold W , whose dimension is $n - 1$. Hence, the index of
05 the quadratic form $(\partial^2 F / \partial w^2)(\theta, w)$ belongs to $\{0, \dots, n - 1\}$. Since $\text{ind}_{C_\sigma}(\gamma)$ is by
06 definition the difference of two such indices, the inequality follows.

07 To prove the claim, observe that the restriction of π to W is locally an immersion.
08 The condition $(\partial F / \partial w)(\theta, w) = 0$ selects those $(\theta, w) \in S^{n-1} \times W$ such that θ , when
09 interpreted as unit vector in \mathbb{R}^n , is orthogonal to the hyperplane $D\pi_w(T_w W) \subset$
10 $T_{\pi(w)}\mathbb{R}^n$. On the other hand, a Legendrian lift of $\pi(W)$ (W itself is such a lift)
11 is nothing but a continuous choice of one of these two vectors at each w . Hence,
12 $W \subset \mathcal{L}$. \square

13
14 Suppose that a generic Legendrian submanifold is such that one can find a path γ
15 with endpoints outside of C_σ such that $|\text{ind}_{C_\sigma}(\gamma)| \geq n$. Then the above Proposition
16 implies that C_π must be non-empty. In the next section, several constructions of
17 Legendrian submanifolds satisfying this hypothesis are proposed.

18 4. Constructions of Legendrian submanifolds

19
20 The following theorem is essentially due to Chekanov [8]. As formulated below,
21 the formal proof can be found in [21], and is implicit in several other papers
22 where proofs of Chekanov’s theorem are given, such as [6, 10, 11, 15]. Consider a
23 generating family $F : S^{n-1} \times V \rightarrow \mathbb{R}$, where V is a closed manifold, and denote by
24 $L_F \subset J^1(S^{n-1}, \mathbb{R})$ the Legendrian submanifold induced by F as in Section 3.2.

25
26 THEOREM. If $L_t \subset J^1(S^{n-1}, \mathbb{R}), t \in [0, 1]$ is a smooth one-parameter family
27 of Legendrian embeddings such that $L_0 = L_F$, then there exists $k \in \mathbb{N}$ and a
28 one-parameter family of functions $F_t : S^{n-1} \times V \times \mathbb{R}^{2k} \rightarrow \mathbb{R}, t \in [0, 1]$ such that
29 $L_t = L_{F_t}$. Furthermore, one can assume that F_t is equal to a fixed quadratic form
30 of index k of the vector variable outside a compact set.

31
32 The Morse inequalities for these functions, which are standard at infinity, reads
33 as follows.

34
35 LEMMA. Let $H : V \times \mathbb{R}^{2k} \rightarrow \mathbb{R}$ be a Morse function which is equal to a quadratic
36 form of index k outside a compact set. The number of critical points of index $k + i$
37 is not less than the dimension of $H^i(V, \mathbb{Z}/2\mathbb{Z})$.

38
39 This lemma is proved in [7] in the case when V is the torus T^n . The same
40 argument works for any compact manifold V .

41
42 PROPOSITION. Assume that L_F is connected. Then on any generic L Legendrian
43 isotopic to L_F there exists a path γ such that $\text{ind}_{C_\sigma} = \dim(V)$.

44
45 Proof. By the theorem above, there exists a one-parameter family of functions
46 $F_t : S^{n-1} \times V \times \mathbb{R}^{2k} \rightarrow \mathbb{R}, t \in [0, 1]$ which induces a path $L_t, t \in [0, 1]$ of embedded
47 Legendrian submanifolds such that $L_0 = L_F$ and $L_1 = L$. For a generic $\theta \in S^{n-1}$,
48 the Morse function $F_1(\theta, \cdot)$ has a critical point a_0 of index k and a critical point
49 $a_{\dim(V)}$ of index $k + \dim(V)$. These two critical points correspond to two points A_0

01 and $A_{\dim(V)}$ on $L \setminus C_\sigma$. Since L is connected, one can join these two points by a
 02 path γ , which is such that $|\text{ind}_{C_\sigma}(\gamma)| = \dim(V)$. \square

03
 04 **REMARK.** The definition of generating families (Section 3.2) implies that the
 05 Legendrian submanifold associated to a generating family $F : S^{n-1} \times V \rightarrow \mathbb{R}$ is
 06 parameterized by the *critical set* of this family, that is the subset $(\partial f / \partial y)(x, y) = 0$
 07 of $S^{n-1} \times V$, which is a smooth $(n - 1)$ -dimensional submanifold according to the
 08 transversality assumption.

09
 10 To prove the Main Theorem, families of functions on the sphere with a connected
 11 critical set have to be constructed. This is the goal of the following propositions.

12
 13 **PROPOSITION A.** *There exists a closed manifold V of dimension n and a generic*
 14 *function $F : S^{n-1} \times V \rightarrow \mathbb{R}$ such that L_F is a connected embedded Legendrian*
 15 *submanifold of $J^1(S^{n-1}, \mathbb{R})$ which is Legendrian homotopic to a Legendrian sub-*
 16 *manifold whose Euclidean front is embedded.*

17
 18 Proposition A, proved in Section 4.2, implies the Main Theorem. We present
 19 in Section 4.3 a different approach which also provides another proof of the Main
 20 Theorem in the case $n = 2$, as follows.

21
 22 **PROPOSITION B.** *For any $k > 0$, there exists a function $F : S^1 \times S^k \rightarrow \mathbb{R}$ such*
 23 *that $L_F \subset J^1(S^1, \mathbb{R})$ is connected.*

24
 25 In dimension 2 the Maslov class is the only homotopic obstruction to cusp
 26 cancellation (see, for example, [14]). It follows from its definition that the Maslov
 27 class is trivial for a Legendrian submanifold which is globally parameterized by
 28 a generating family. Hence, one can deform the Legendrian submanifold whose
 29 existence is asserted in Proposition B through Legendrian immersions to the effect
 30 that the resulting Euclidean front is an immersed curve.

31
 32 **PROPOSITION C.** *For any $k > 1$ and any connected manifold N such that*
 33 *$\dim N > 1$, there exists a function $F : N \times \mathbb{R}P^k \rightarrow \mathbb{R}$ such that L_F is a connected*
 34 *Legendrian submanifold of $J^1(N, \mathbb{R})$. In addition, this function F can be chosen to*
 35 *be quadratic with respect to the $\mathbb{R}P^k$ factor (i.e. $F(q, \cdot)$ is a function induced on*
 36 *$\mathbb{R}P^k$ by a quadratic form of \mathbb{R}^{k+1}).*

37
 38 **PROPOSITION D.** *For any compact connected manifold W and any connected*
 39 *manifold N of positive dimension, there exists a function $F : N \times W \rightarrow \mathbb{R}$ such*
 40 *that L_F is a connected Legendrian submanifold of $J^1(N, \mathbb{R})$.*

41
 42 The proofs of Propositions C and D are given in Sections 4.4 and 4.5, respectively.
 43 Using another construction, Entov has given other examples of fronts in $J^0(S^2, \mathbb{R})$
 44 with ‘a lot of’ singularities (see [13, Proposition 10.1]).

45
 46 **4.1. A remark about Propositions C and D**

47
 48 In the case when $N = S^{n-1}$, Propositions C and D give us some L_F for which both **Q3**
 49 the 0-jets front and the Euclidean front have ‘a lot of’ singularities which are not

01 removable by a deformation through Legendrian embeddings. On the other hand,
 02 we cannot ensure that these L_F can be deformed through Legendrian immersions
 03 to some L' with an immersed Euclidean front.

04 We can, however, ensure that our examples are *Legendre-cobordant* to a Leg-
 05 endrian submanifold whose 0-jets front and Euclidean front are both immersed
 06 (see [4, Chapter 6] for basic details about Legendrian cobordism). In particular the
 07 obstructions to the elimination of singularities found by Vassiliev [22] vanish for
 08 the L_F whose existence is asserted by Propositions C and D.

09
 10 PROPOSITION. Any Legendrian submanifold of $J^1(S^{n-1}, \mathbb{R})$ which is globally
 11 induced by a generating family $F : S^{n-1} \times V \rightarrow \mathbb{R}$ is Legendre-cobordant to a
 12 Legendrian submanifold L whose 0-jets and Euclidean fronts are both immersed.

13
 14 *Proof.* Consider a ‘constant’ generating family $F_1 : S^{n-1} \times V \rightarrow \mathbb{R}$ of the form
 15 $F_1(q, v) = f_1(v)$, where f_1 is a Morse function without multiple critical values on V .
 16 The 0-jets front of L_{F_1} consists of a number of ‘parallel’ copies of S^{n-1} in $S^{n-1} \times \mathbb{R}$.
 17 The corresponding Euclidean front consists of the same number of concentric round
 18 spheres provided that f_1 has no vanishing critical value. Consider some function
 19 $\tilde{F} : S^{n-1} \times [0, 1] \times V \rightarrow \mathbb{R}$ such that $\tilde{F}(\theta, 0, v) = F(\theta, v)$ and $\tilde{F}(\theta, 1, v) = F_1(\theta, v)$.
 20 One can assume that \tilde{F} fulfills the transversality condition, so that it induces
 21 some embedded Legendrian submanifold $L_{\tilde{F}} \subset J^1(S^{n-1} \times [0, 1], \mathbb{R})$ which realizes
 22 a Legendrian cobordism between L_F and L_{F_1} . \square

23 4.2. Proof of Proposition A

24
 25 4.2.1. *Apparent contours.* Let V and M be two n -dimensional manifolds. Sup-
 26 pose that V is immersed in $M \times \mathbb{R}$. We will abusively identify V with its immersed
 27 image in $M \times \mathbb{R}$. Denote by φ the standard projection $\varphi : M \times \mathbb{R} \rightarrow M$, and by
 28 $\mathcal{C} \subset ST^*(M \times \mathbb{R})$ the set of cooriented contact elements of $M \times \mathbb{R}$ which are tangent
 29 to the fiber of φ . Denote by $L_V \subset ST^*(M \times \mathbb{R})$ the set of cooriented contact elements
 30 of $M \times \mathbb{R}$ which are tangent to V . Observe that V is covered twice by L_V . It follows
 31 from [4, Chapter 5, Section 1.2] that if L_V is transversal to \mathcal{C} , then the image of
 32 $L_V \cap \mathcal{C}$ by the natural projection $\mathcal{C} \rightarrow ST^*M$ is an immersed (generically embedded)
 33 Legendrian submanifold $L \subset ST^*M$. Its front $\pi(L)$ is called the *apparent contour*
 34 of V . This terminology comes from the fact that, when $n = 2$ and M is the plane,
 35 this front is the usual apparent contour of the immersed surface V in \mathbb{R}^3 . Note that
 36 $\pi(L)$ is not a generic front: $\pi|_L : L \rightarrow \pi(L)$ is two to one. Hence, L is connected if
 37 and only if the apparent contour of V is connected and *not* coorientable in \mathbb{R}^n .

38
 39 4.2.2. *Generating families for apparent contours in the Euclidean space.* We
 40 keep the same notation, but we specialize to the case when M is the Euclidean
 41 space \mathbb{R}^n .

42
 43 LEMMA. Suppose that the above transversality assumption holds. The function
 44 $F : S^{n-1} \times V$ defined by

$$45 \quad F : S^{n-1} \times V \rightarrow \mathbb{R}$$

$$46 \quad F(\theta, v) = \langle \varphi(v), \theta \rangle$$

47
 48 is a generating family for the Legendrian submanifold $L \subset J^1(S^{n-1}, \mathbb{R}) \equiv ST^*\mathbb{R}^n$.

49
 50

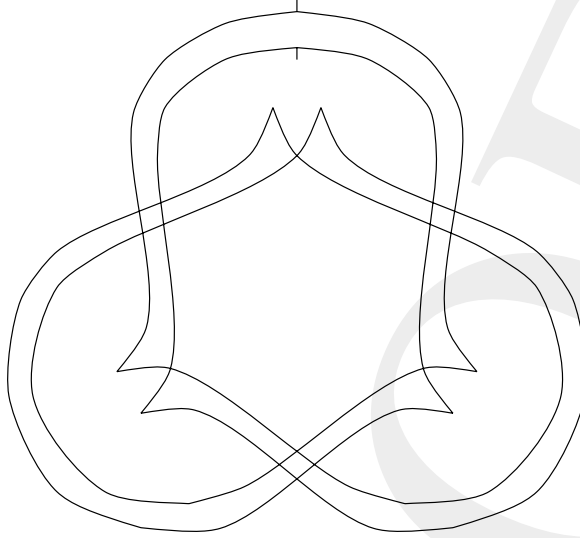


FIGURE 1. A cooriented planar front from which at least two of the cusps cannot be eliminated by means of a Legendrian isotopy.

Proof. The condition $(\partial F/\partial v)(\theta, v) = 0$ implies that we are considering those (θ, v) such that $\langle \varphi_*(X), \theta \rangle = 0$ for all $X \in T_v V$. This implies that $\varphi|_V$ is not a submersion at v , because the image of its differential is included in a hyperplane. In other words, the tangent hyperplane to V at v contains the line tangent to the fiber of φ at v , and $\varphi(v)$ lies in the apparent contour of V . \square

4.2.3. *Proof of Proposition A in the case $n = 2$.* In the planar case, we take advantage of the fact that the number of cusps in a generic apparent contour of a surface has the parity of the Euler characteristic of this surface (see [19] for references about this classical subject).

LEMMA. *There exists an immersion of $\mathbb{R}P^2$ in $\mathbb{R}^2 \times \mathbb{R}$ whose (non-coorientable) apparent contour is connected. Furthermore, the corresponding Legendrian submanifold in $ST^*\mathbb{R}^2$ is Legendrian homotopic to a Legendrian submanifold whose Euclidean front is embedded.*

Proof. The apparent contour of the Boy immersion [5] with respect to the projection along its axis of symmetry is connected and has three cusps. The transversality assumption is fulfilled. The corresponding Legendrian submanifold is the (connected) double cover of this front. The Euclidean front of a slight perturbation of this Legendrian submanifold is shown in Figure 1. Figure 2 details the projection to the plane of a Legendrian homotopy between this Legendrian submanifold and the Legendrian lift of a cooriented circle. In the beginning of this homotopy, the fronts (with an odd number of cusps) are kept non-generic. \square

By this approach, to any generic immersion of a surface in $\mathbb{R}^2 \times \mathbb{R}$ whose apparent contour in \mathbb{R}^2 is a connected front with an odd number of cusps, one can associate

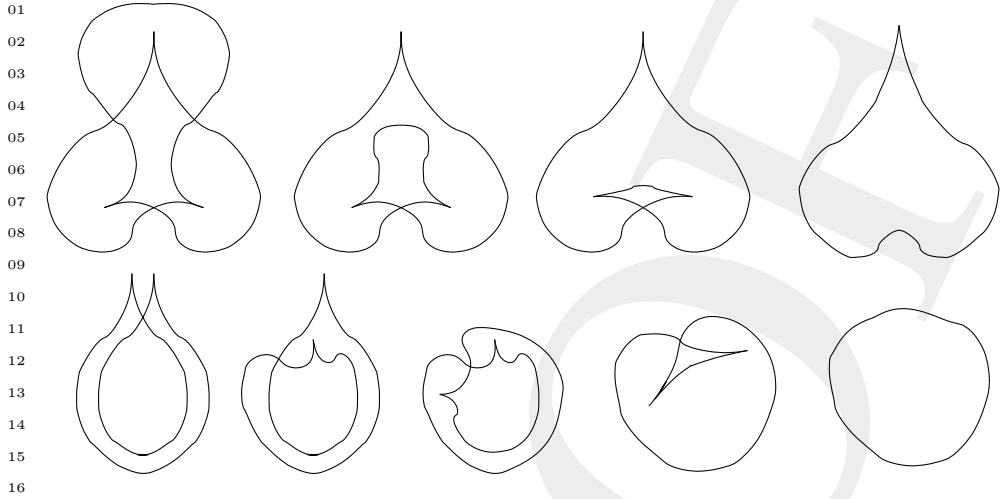


FIGURE 2. From the contour of the Boy surface to a circle.

a Legendre isotopy class all of whose representatives have a non-immersed front. Many such immersions exist for any surface with an odd Euler characteristic. Using the Boy immersion, we obtained a planar front with six cusps, such that at least two of them are ‘non-removable’. The immersion of $\mathbb{R}P^2$ described in [19], whose contour consists of a fairly complicated connected curve with one single cusp, would provide us with an example with only two cusps, which are non-removable.

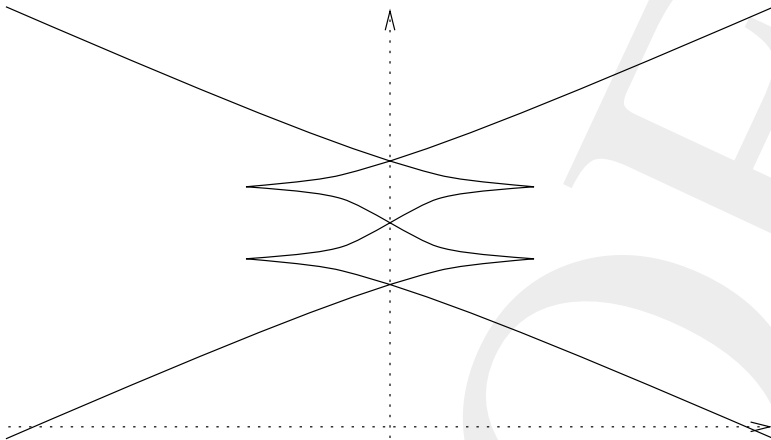
This proves Proposition A in the case $n = 2$. The general case follows from this particular case via the following construction.

4.2.4. *Rotating our 2-dimensional example.* Consider again an immersion V in $M \times \mathbb{R}$ as in Section 4.2.1, an arbitrary manifold N , and the trivial product immersion of $V \times N$ in $M \times N \times \mathbb{R}$. If the transversality condition holds for the immersion of V , then it also holds for the product immersion of $V \times N$. The apparent contour of $V \times N$ in $\mathbb{R}^n \times N$ is the product by N of the apparent contour of V in M .

Hence, for any $n > 2$ there exists some immersions of $\mathbb{R}P^2 \times T^{n-2}$ in $\mathbb{R}^2 \times T^{n-2} \times \mathbb{R}$ satisfying the transversality condition, whose apparent contours in $\mathbb{R}^2 \times T^{n-2}$ are connected (T^{n-2} denotes the $(n-2)$ -dimensional torus). However, $\mathbb{R}^2 \times T^{n-2}$ can be realized as a small tubular neighborhood of a standard codimension 2 torus $T^{n-2} \subset \mathbb{R}^n$. In this way, we obtain immersions of $\mathbb{R}P^2 \times T^{n-2}$ in $\mathbb{R}^n \times \mathbb{R}$ whose apparent contours in \mathbb{R}^n are connected, or, according to Section 4.2.2, connected Legendrian submanifolds of $J^1(S^{n-1}, \mathbb{R}) \cong ST^*\mathbb{R}^n$ which are induced by a generating family with auxiliary space $\mathbb{R}P^2 \times T^{n-2}$.

By the same product trick, one can construct in a trivial way, from a Legendrian homotopy which eliminates the cusps of the apparent contour of the Boy immersion in the planar case, a Legendrian homotopy which eliminates C_π for this higher dimensional example. This proves Proposition A and, hence, the Main Theorem.

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16 FIGURE 3. The 0-jets front of the Legendrian submanifold of $J^1(\mathbb{R}, \mathbb{R})$ induced by G .

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19 **4.3. Proof of Proposition B**

20
21 Consider a diagonal matrix $A = \text{diag}(r_1, \dots, r_k)$ such that $r_i \neq r_j$ if $i \neq j$, a
22 vector $Y = (y_1, \dots, y_k)$ such that $y_i \neq 0$ for all $i \in \{1, \dots, k\}$, and the function

23
24
$$G : \mathbb{R} \times S^{k-1} \rightarrow \mathbb{R}$$

25
$$G(t, X) = \frac{1}{2} \cdot \langle X, AX \rangle + t \cdot \langle Y, X \rangle$$

26 where the sphere S^{k-1} is seen as the unit sphere of \mathbb{R}^k .

27
28 **LEMMA.** *The function $t \rightarrow \#\{dG(t, \cdot) = 0\}$, which associates to the parameter t*
29 *the number of critical points of the function $G(t, \cdot)$ on the sphere, is decreasing on*
30 *$[0, \infty)$.*

31
32 *Proof.* A critical point of $G(t, \cdot)$ is a unit vector $X \in S^{k-1}$ such that there
33 exists a real number r which satisfies $AX + t \cdot Y = r \cdot X$. That is, for all $i \in$
34 $\{1, \dots, k\}$, $r_i x_i + t \cdot y_i = r \cdot x_i$ under the constraint $\sum_{i=1}^k x_i^2 = 1$.

35 Hence, critical points of $G(t, \cdot)$ are in one-to-one correspondence with the solu-
36 tions of $g(r) = 1/t^2$, where the function g is defined by

37
38
$$g(r) = \sum_{i=1}^k \frac{y_i^2}{(r_i - r)^2}.$$

39
40 The fact that g is locally strictly convex ($g'' > 0$) implies the lemma. □

41
42
43 For any $i \in [0, \dots, k - 1]$, the function $G(0, \cdot)$ has two critical points of index i ,
44 which are both sent to the same critical value. Since critical points die in pairs of
45 consecutive indices, the 0-jets front of the Legendrian submanifold induced by G in
46 $J^1(\mathbb{R}, \mathbb{R})$ looks like Figure 3 (in which we have set $k = 2$).

47 Consider a smooth one-parameter family of unit vectors $Y_t, t \in (0, 1)$ such that
48 $Y_t = Y$ for t close to 0, and $Y_t = -Y$ for t close to 1. The function $H : (0, 1) \times S^{k-1} \rightarrow$
49 \mathbb{R} defined by $H(t, X) = \langle X, Y_t \rangle$, viewed as generating family, induces a Legendrian

50

01 submanifold of $J^1((0, 1), \mathbb{R})$ whose 0-jets front is made of two horizontal lines at
 02 levels ± 1 . In terms of functions over the sphere, the family $H(t, \cdot)$ connects the
 03 two ends of the family $G(t, \cdot)$. Hence, by gluing G and H , one obtains a generating
 04 family $F : S^1 \times S^{k-1} \rightarrow \mathbb{R}$ which induces a connected Legendrian submanifold in
 05 $J^1(S^1, \mathbb{R})$. This proves Proposition B.

07 4.4. Proof of Proposition C

09 Denote by $S^2\mathbb{R}^{k+1} = \mathbb{R}^{((k+1) \cdot (k+2))/2}$ the space of all quadratic forms on \mathbb{R}^{k+1} .
 10 Consider a smooth mapping $f : N \rightarrow S^2\mathbb{R}^{k+1}$. One can associate canonically
 11 to f a function $F : N \times \mathbb{R}P^k \rightarrow \mathbb{R}$, since a quadratic form restricted to the
 12 unit sphere is symmetric and descends to a function defined on $\mathbb{R}P^k$. The critical
 13 points (respectively critical values) of $F(x, \cdot)$ are the eigendirections (respectively
 14 eigenvalues) of $f(x)$.

15 Remark that if f is a constant map with value a quadratic form all of whose
 16 eigenvalues are distinct, then the 0-jets front of the corresponding $L_F \subset J^1(N, \mathbb{R})$
 17 is made of $k + 1$ 'parallel layers' (each layer being a copy of N) in $N \times \mathbb{R}$. In the
 18 following we indicate how to modify locally such an f to the effect that all of these
 19 layers are connected.

20 CLAIM. *It is enough to describe a connection model for the case $k = 1$.*

22 Proof. Consider some $f : N \rightarrow S^2\mathbb{R}^{k+1}$ of the form $f = f_1 \oplus f_2$, with $f_i : N \rightarrow S^2\mathbb{R}^{k_i}$ ($k_1 + k_2 = k + 1$). Denote by $F : N \times \mathbb{R}P^k \rightarrow \mathbb{R}$ (respectively $F_i : N \times \mathbb{R}P^{k_i-1} \rightarrow \mathbb{R}, i \in \{1, 2\}$) the corresponding functions. Assuming that, for all $q \in N$, the eigenvalues of $f_1(q)$ are strictly larger than those of $f_2(q)$, we have that L_F is the disjoint union of L_{F_1} and L_{F_2} . Hence, in order to connect two layers, it is enough to consider the case $k = 1$ provided that the resulting connecting model between the two layers produces a connected front contained within a small neighborhood of the region of $J^0(N, \mathbb{R})$ delimited by these two layers. \square

31 An element of $S^2\mathbb{R}^2$ can be described by three coordinates (a, b, c) as follows:

$$33 \begin{pmatrix} a+b & c \\ c & a-b \end{pmatrix}.$$

34 Such a quadratic form has two equal eigenvalues if and only if $b = c = 0$.

36 LEMMA. *If some $f : N \rightarrow S^2\mathbb{R}^2$ is transversal to the axis $\{b = c = 0\}$, then the corresponding generating function $F : N \times \mathbb{R}P^2 \rightarrow \mathbb{R}$ is such that L_F is an embedded Legendrian submanifold of $J^1(N, \mathbb{R})$.*

38 Proof. The transversality assumption implies that $D = f^{-1}(\{b = c = 0\})$
 39 is a smooth submanifold of N . If q is not in D , then L_F is embedded above
 40 a neighborhood of q , because in that case $F(q, \cdot)$ is a Morse function. On the
 41 other hand, one can describe a neighborhood in N of some $q \in D$ by some local
 42 coordinates (x, y, z) , $(x, y) \in \mathbb{R}^2$, $z \in D$, such that the mapping f can be written

$$43 f : (x, y, z) \rightarrow \begin{pmatrix} a(z) + x & y \\ y & a(z) - x \end{pmatrix},$$

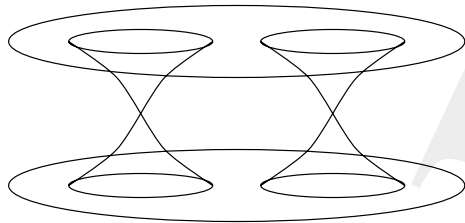


FIGURE 4. *The connecting model.*

where a is some unknown function of z . The corresponding F is given by the formula

$$F(x, y, z, \theta) = a(z) + x \cdot \cos(2 \cdot \theta) + y \cdot \sin(2 \cdot \theta),$$

where the point $[\cos(\theta) : \sin(\theta)]$ of $\mathbb{R}P^1$ is represented by θ . From this explicit formula, a computation shows that L_F is an embedded Legendrian submanifold. This proves the lemma. \square

With this lemma, we can proceed to the description of the connecting model. Fix a small open ball $B \subset N$, and a smooth function $\rho : N \rightarrow [0, 1]$ such that $B = \rho^{-1}([0, 1])$ and that $\rho^{-1}(0)$ is non-empty. Fix two constants $\lambda \in \mathbb{R}$ and $\mu \in]0, +\infty[$. Define a smooth $f : N \rightarrow S^2\mathbb{R}^2$ by the formula

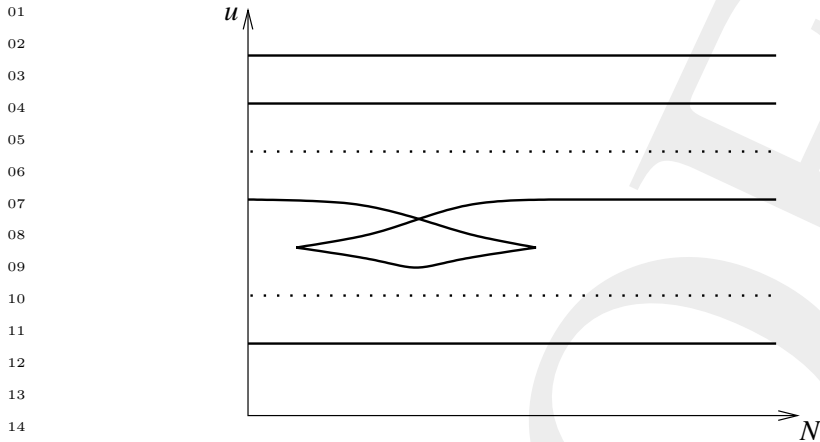
$$f(q) = \begin{pmatrix} \lambda & \rho \cdot \mu \\ \rho \cdot \mu & \lambda \end{pmatrix}.$$

By construction $f^{-1}(\{b = c = 0\}) = \rho^{-1}(0)$ is non-empty, but this intersection is non-transversal. After a small perturbation inside $\rho^{-1}([0, \epsilon])$, for some small ϵ , one can assume that $f(N)$ has a non-empty transversal intersection with $\{b = c = 0\}$ along some smooth submanifold $D \subset B$. Furthermore, if the perturbation is small enough, one can assume that the eigenvalues of $f(q)$ lie in $[\lambda - \mu, \lambda + \mu]$ for all $q \in N$. The corresponding L_F is connected: consider some point $q_0 \in D$. Denote by $J_{q_0}^1(N, \mathbb{R})$ the fiber $\sigma^{-1}(\{q_0\} \times \mathbb{R})$ of the one-jets space above q_0 (that is, $J_{q_0}^1(N, \mathbb{R}) = T_{q_0}^*N \times \mathbb{R}$). Observe that since $q_0 \in D$, then $L_F \cap J_{q_0}^1(N, \mathbb{R})$ is diffeomorphic to $\mathbb{R}P^1$ and, hence, connected. Consider some point $A \in L_F$ and its projection q on N . Any path γ from q_0 to q which avoids the codimension 2 subset D (except at q_0) can be lifted unambiguously to a path in L_F joining $L_F \cap J_{q_0}^1(N, \mathbb{R})$ to A . This shows that L_F is connected, and this finishes the proof of Proposition C.

REMARK. The 0-jets front of this L_F is highly non-generic, its singularities form a set of codimension 2. In the case $k = 1$, the connection looks as in Figure 4 near D .

4.5. Proof of Proposition D

The idea is to start from a Legendrian submanifold induced by a generating family $G : N \times W \rightarrow \mathbb{R}$, of the form $G(q, w) = f(w)$, where f is some Morse function with distinct critical values. The corresponding Legendrian submanifold $L_G \subset J^1(N, \mathbb{R})$ is diffeomorphic to the disjoint union of some ‘parallel’ copies of N .

FIGURE 5. *Creation of local minima.*

Our goal is to describe how to modify locally this family of functions in order to connect these components.

4.5.1. Consider some generating family $G : N \times W \rightarrow \mathbb{R}$ and its associated Legendrian submanifold $L_G \subset J^1(N, \mathbb{R})$. Each point $x \in L_G$ corresponds to some point $(q, w) \in N \times W$. Denote by $\text{ind}_G(x)$ the Morse index of the function $G(q, \cdot) : W \rightarrow \mathbb{R}$ at its critical point w . Suppose that the function $G(q, \cdot) : W \rightarrow \mathbb{R}$ is a Morse function without multiple critical values. Consider a sufficiently small open neighborhood $U \subset N$ of the point q . For any q_0 in such a neighborhood, the function $G(q_0, \cdot) : W \rightarrow \mathbb{R}$ is a Morse function having distinct critical values. Hence, $L_G \cap J^1(U, \mathbb{R}) \subset J^1(N, \mathbb{R})$ is a disjoint union of some copies of U . Denote by U_x the component which contains the point x . Suppose that $\text{ind}_G(x)$ is positive.

LEMMA 1. *There exists $G_t, t \in [0, 1]$, a C^0 -small deformation of G compactly supported in $U \times W$, such that:*

- for any t , L_{G_t} is an embedded Legendrian submanifold of $J^1(N, \mathbb{R})$;
- U_x is the only component of $L_G \cap J^1(U, \mathbb{R})$ which changes during this deformation; denote by $U_x(t)$ the corresponding deformation of the component U_x ;
- there exists a point $q_0 \in U$ such that $G_1(q_0, \cdot)$ is a Morse function without multiple critical values, and there exist a unique critical point $x_0 \in U_x(1)$ above q_0 such that $\text{ind}_{G_1}(x_0) = \text{ind}_G(x) - 1$;
- the family G_1 does not depend on $q \in N$ near q_0 : $G_1(q, w) = G_1(q_0, w)$ for q sufficiently close to q_0 .

Proof. We can assume (after a C^0 -small deformation of G and choosing a smaller neighborhood if needed) that we are starting with a generating family which does not depend on the coordinate q . In the case $\dim N = 1$ the deformation G_t is obtained by creating a small ‘triangle’ on the front of L_G , as shown in Figure 5 (see, for example, [18] for similar constructions). In this case we identify U with

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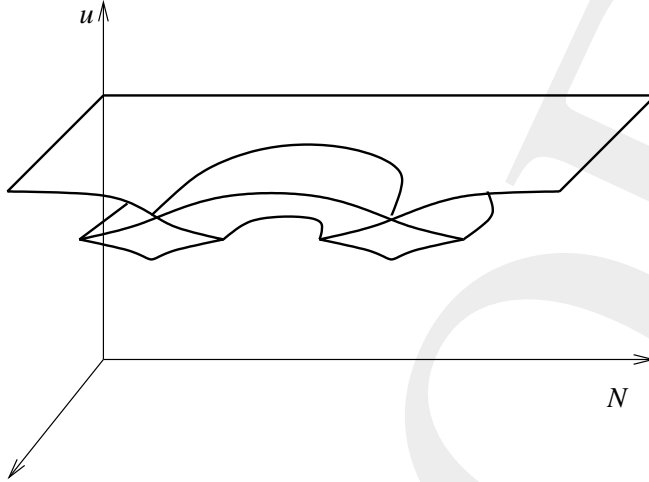


FIGURE 6. Rotating the one-dimensional model.

the interval $]0, 1[$, and we denote this deformation by $g_t(q, w)$, $q \in]0, 1[$. In the case when $\dim N > 1$, we just ‘rotate’ this one-dimensional model: We consider spherical coordinates on U , thinking of U as a ball of radius 1. We can take a deformation depending only on the radius $r(q)$, that is, of the form $G_t(q, w) = g_t(r(q), w)$. If $\dim N = 2$, then the front will locally look like in Figure 6. \square

4.5.2. We now begin the proof of Proposition D. Let $f : W \rightarrow \mathbb{R}$ be a Morse function without multiple critical values, having exactly one minimum $f(w_0)$ at some $w_0 \in W$. Denote by w_1, \dots, w_k its other critical points, and by $u_k = f(w_k)$ its critical values. Consider the function $G : N \times W \rightarrow \mathbb{R}$, defined by $G(q, w) = f(w)$. It is a generating family of a Legendrian manifold $L_G \subset J^1(N, \mathbb{R})$ which is diffeomorphic to the disjoint union of $(k + 1)$ -copies of $N : L_G = L_0 \cup \dots \cup L_k$. Consider some $i > 0$ and a point $x \in L_i$, corresponding to $(q, w_i) \in N \times W$. After applying Lemma 1 sufficiently many times, we can find a deformation G_t of G such that:

- all components $L_j(t), j \neq i$ do not depend on t ;
- the component L_i undergoes a C^0 -small deformation in a neighborhood of x ;
- there exist a point q_0 near q such that $G_1(q_0, \cdot)$ is a Morse function with distinct critical values having exactly two local minima, one at the point w_0 (which is also a global minimum) and the other at a point w_i near w_i (this corresponds to a point in the deformed component $L_i(1)$).

LEMMA 2. *The deformed function $G_1(q_0, \cdot)$ has a critical point a_i of index 1 near the point w_i , such that for any gradient-like vector field v adapted to the function $G_1(q_0, \cdot)$, there is exactly one trajectory of v connecting a_i and w_i .* Q4

Proof. Due to our construction, the function $G_1(q_0, \cdot)$ is a C^0 -small deformation of the function f . This deformation is compactly supported near the point w_i .

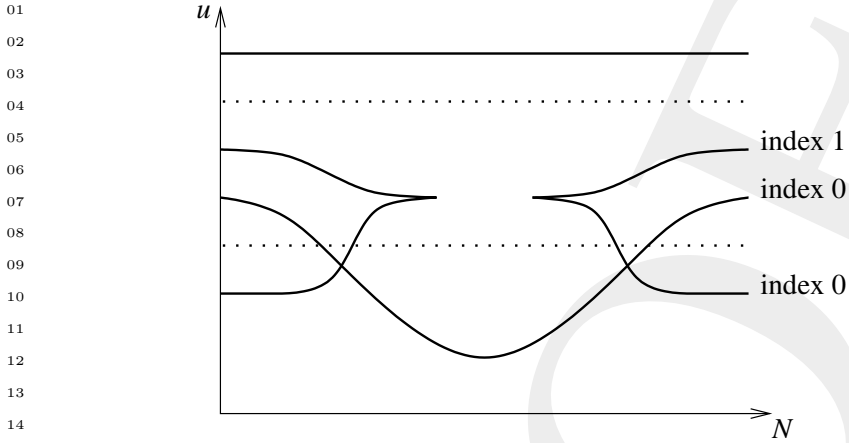


FIGURE 7. The death–birth of a pair of critical points of index 0 and 1.

Hence, (if the deformation is chosen sufficiently small) for a suitable $\varepsilon > 0$, the two pairs of sets

$$(\{w \in W \mid G_1(q_0, w) \leq u_i + \varepsilon\}, \{w \in W \mid G_1(q_0, w) \leq u_i - \varepsilon\})$$

and

$$(\{w \in W \mid f(w) \leq u_i + \varepsilon\}, \{w \in W \mid f(w) \leq u_i - \varepsilon\})$$

are exactly the same. Denote the two sets of this pair by $W^{u_i \pm \varepsilon}$. On one hand, the homology groups $H_*(W^{u_i + \varepsilon}, W^{u_i - \varepsilon})$ can be calculated with the help of the Thom–Smale–Witten complex of $G_1(q_0, \cdot)$. On the other hand, $H_j(W^{u_i + \varepsilon}, W^{u_i - \varepsilon})$ is non-zero if and only if $j = \text{ind}(w_i) = \text{ind}_G(x)$. Hence, $H_0(W^{u_i + \varepsilon}, W^{u_i - \varepsilon}) = 0$, which implies that there must be a trajectory connecting the critical point a_i of index 1 to w_i . Note that since a_i is of index 1, there are exactly two trajectories emanating from it. One goes to the global minimum, the other to w_i . \square

LEMMA 3. Let $h : W \rightarrow \mathbb{R}$ be a Morse function without multiple critical values, having exactly two local minima w_0, ω . Suppose that there exists a gradient-like vector field v adapted to h with two trajectories connecting a critical point a of index 1 to w_0 and ω . Then there exists a one-parameter family $g_t : W \rightarrow \mathbb{R}, t \in [-1, 1]$ of functions such that

- the family g_t is symmetric $g_t(w) = g_{-t}(w)$;
- the family g_t is constant and equal to h for t close to ± 1 , and independent of the variable t for t close to 0;
- the front of the Legendrian submanifold of $J^1([-1, 1], \mathbb{R})$ induced by the family $g_t, t \in [-1, 1]$ has exactly two cusps, the first corresponding to the cancellation of points a and w_0 , the second to the rebirth of these two critical points (see Figure 7).

Proof. This follows from the standard model of the cancellation of a pair of critical points joined by a single trajectory (see, for example, [18]). \square

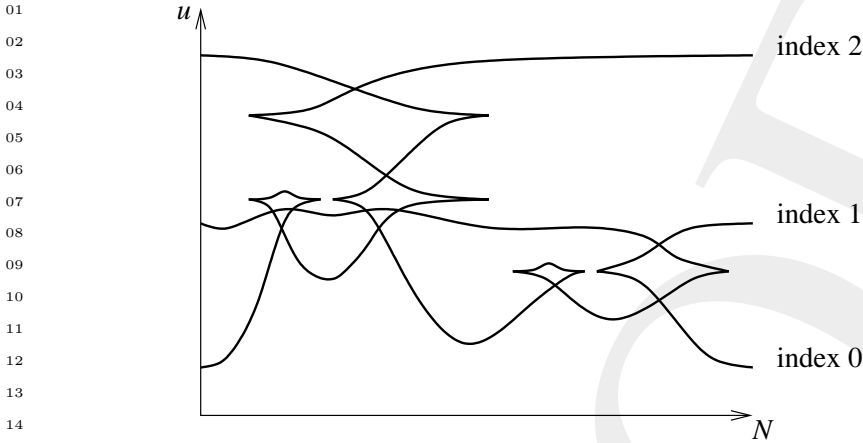


FIGURE 8. An example with $\dim N = 1$ and $W = \mathbb{R}P^2$.

In the case $\dim N = 1$, we finish the proof of Proposition D by applying Lemma 3 (with $h = G_1(q_0, \cdot)$) in a small neighborhood of the point q_0 constructed above. This reduces the number of connected components. In the other cases, we ‘rotate’ this one-dimensional model (this is possible because it is symmetric). We consider a neighborhood U of the point q_0 , and spherical coordinates centered at q_0 . Then we replace the generating family $G_1(q, w)$ by $g_r(q)(w)$, where r denote the radius function. This operation connects the layer L_i with the layer L_0 of the Legendrian submanifold L_G we started with. This finishes the proof of Proposition D. In the case when $\dim N = 1$, $W = \mathbb{R}P^2$ and the starting function f is a function with one critical point of each index, the result of this process is shown in Figure 8.

REMARK. The connected Legendrian submanifolds constructed here have only the most simple singularities (folds) with respect to the projection $J^1(N, \mathbb{R}) \rightarrow N$. The folds are along spheres. Furthermore, these Legendrian submanifolds are diffeomorphic to the connected sum of $k + 1$ copies of N .

5. Final remarks

All of the Legendrian submanifolds constructed in Propositions A, B, C and D are of the form L_G , for some generating family $G : N \times W \rightarrow \mathbb{R}$. In the case $N = S^1$, this implies that *none of these Legendrian knots can be embedded in an ball embedded in $J^1(S^1, \mathbb{R})$* (see [14]).

Furthermore, one can check that, up to sign, the degree of their ‘Gauss map’ (that is, the restriction of the projection $J^1(S^1, \mathbb{R}) \rightarrow S^1$ to the Legendrian submanifold under consideration) is equal to the Euler characteristic of the auxiliary manifold W .

The key property of the Legendrian *knots* constructed in Propositions A, B and D is that, on any knot in the same Legendrian isotopy class, there exists pairs of points with a large relative Maslov index. It is likely that a similar property could be proved using contact homology (for example, in its combinatorial version [9], suitably adapted for Legendrian knots is $J^1(S^1, \mathbb{R})$).

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AUTHOR QUERIES

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Q1 (page 2):

Editor: Secondary classification ok?

Q2 (page 4):

Author: Please check that the sense of ‘Legendrian ... front’ is as intended

Q3 (page 7):

Author: We have changed ‘Proposition C’ to ‘Proposition D’ throughout as there was no ‘Proposition C’, ok?

Q4 (page 15):

Author: Lowercase ‘*u*’ as intended in Figures 5–8 or should it be uppercase ‘*U*’?

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